Mechanically Jointed Rodless Cylinder

MY2 Series

ø16, ø25, ø40

Compact and low profile design

Mechanically Jointed Rodless Cylinder

MY2 Series

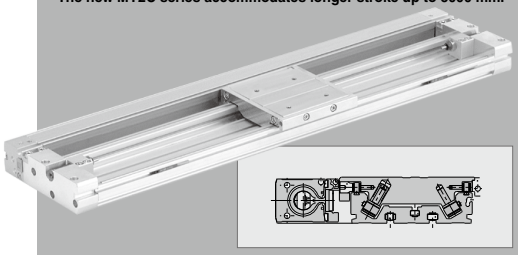
Compact and low profile design

A complete reduction in height of the cylinder allows mounting in a narrow space.
The low profile design of the cylinder built with a high precision single or double axis guide, provides same load capacity as the earlier MY1 series.
Three types of guide options to suit a variety of applications.

MY2C Cam Follower Guide

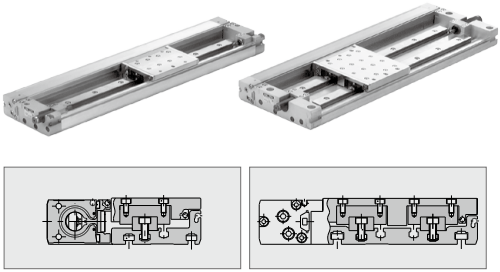
Available with long stroke

The new MY2C series accommodates longer stroke up to 5000 mm.



MY2H Single-axis Linear Guide

MY2HT Double-axis Linear Guide



All 3 types have the same cylinder height and actuator (cylinder).

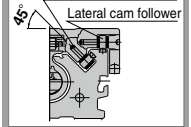
Increased load capacity

The dynamic load mass has been increased with improved guide performance. (Compared to previous MY1 series.)

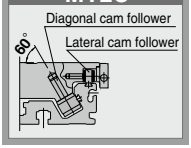
Cam Follower Guide | **Linear Guide**

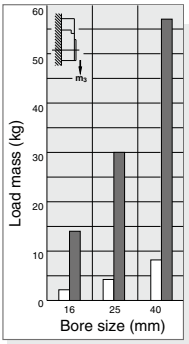
Higher rigidity of the diagonal cam follower and change in the mounting angle provides improved load and moment capacity.

MY1C

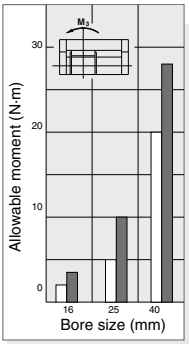


MY2C

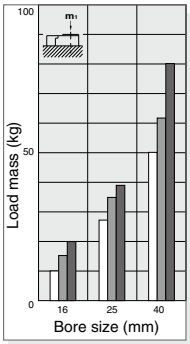




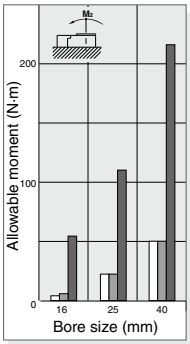
MY2C
MY1C



MY2C
MY1C



MY2HT
MY2H
MY1H

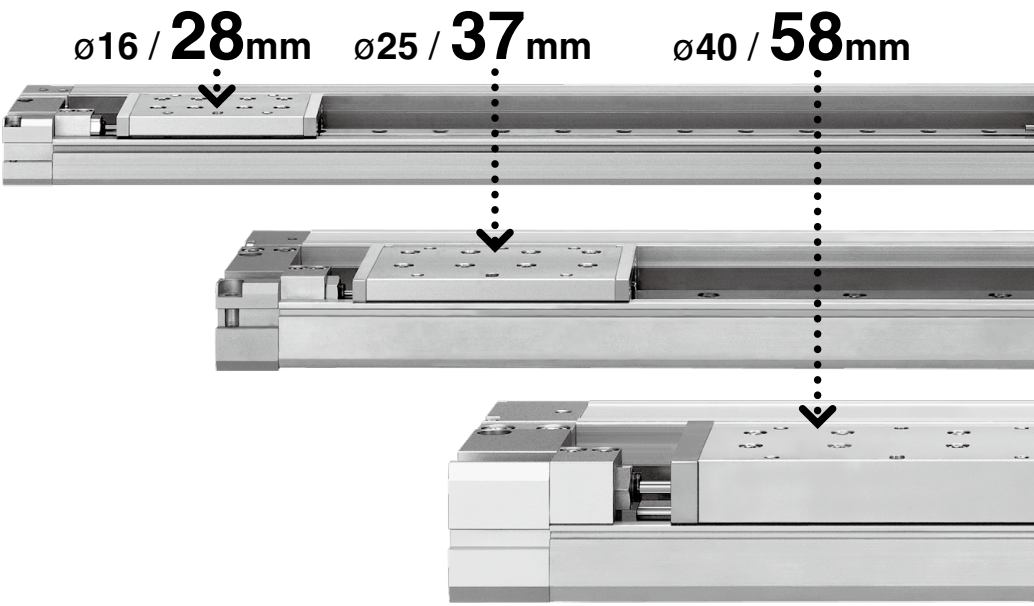


MY2HT
MY2H
MY1H

Height reduction by 30% (Compared to previous MY1 series.)

Low profile achieved by placing the guide unit and cylinder body next to one another. (dimension reduced by 12 mm to 26 mm)

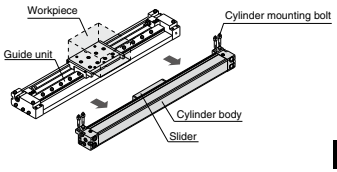
Series	ø16	ø25	ø40
MY2C			
MY2H (Single axis)	28	37	58
MY2HT (Double axis)			
MY1C, MY1H	40	54	84



Easy replacement of cylinder body

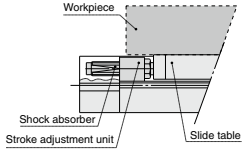
The cylinder can be replaced without removing the workpiece

The cylinder can be detached by simply removing the four mounting bolts, and pulling it off in the direction of the arrows.



Improved mounting flexibility

The low profile design allows mounting of heavy-loaded shock absorber (H unit) without interfering with the workpiece.

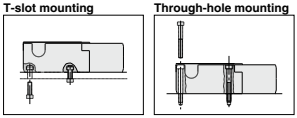


Option

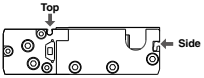
Optional side support is available (MY2C series)

A side support prevents guide deflection for the long stroke application.

Two mounting types



Auto switch mounting on two sides



Standard with air cushion and centralized piping

Series Variations

Model	Bore size (mm)	Standard stroke (mm) 50 100 150 200 250 300 350 400 450 500 550 600 700 800 900 1000 1200 1400 1600 1800 2000	Max. available stroke (mm)	Made to order
MY2C Cam follower guide	16		5000 (3000 for ø16)	· Helical insert threads · Shock absorber soft type RJ series mounted
MY2H Linear guide/Single axis	25		1500 (1000 for ø16)	
MY2HT Linear guide/Double axis	40			

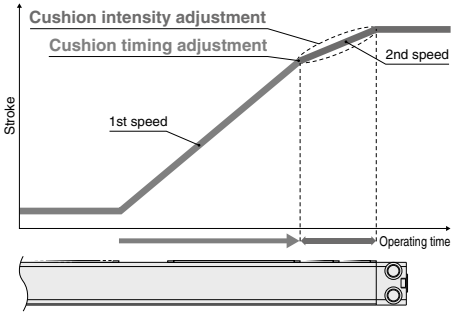
Note) Availability for Made-to-Order differs, depending on the size and the model.

Related Products

Deceleration Controller DAS Series

Click here for details

2-speed control reduces cycle time Allows for the impact relaxation of the stroke end



Allows for the 2-speed control of cylinders

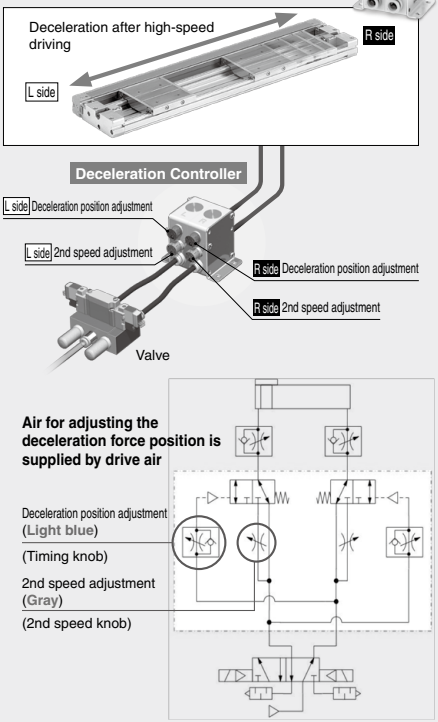
The deceleration position (cushion timing) and

2nd speed (cushion intensity)

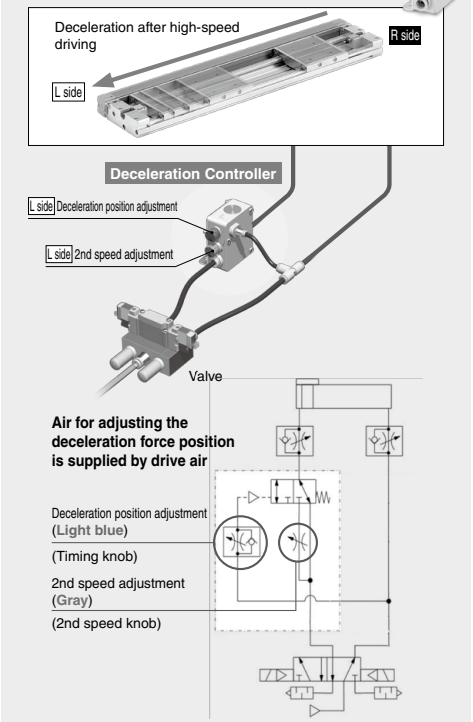
can be adjusted.

■ Piping Example

For double-end



For single-end



Variations

Mounting	Body size	Applicable tubing O.D.										Bore size
		Metric size					Inch size					
		4	6	8	10	12	5/32"	1/4"	5/16"	3/8"	1/2"	
	5	●	●	●	●	●	●	●	●	●	●	ø10 to ø40
	7			●	●	●			●	●	●	Up to ø100

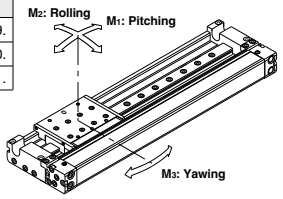
MY2 Series
Model Selection 1

The following are the steps for selection of the MY2 series best suited to your application.

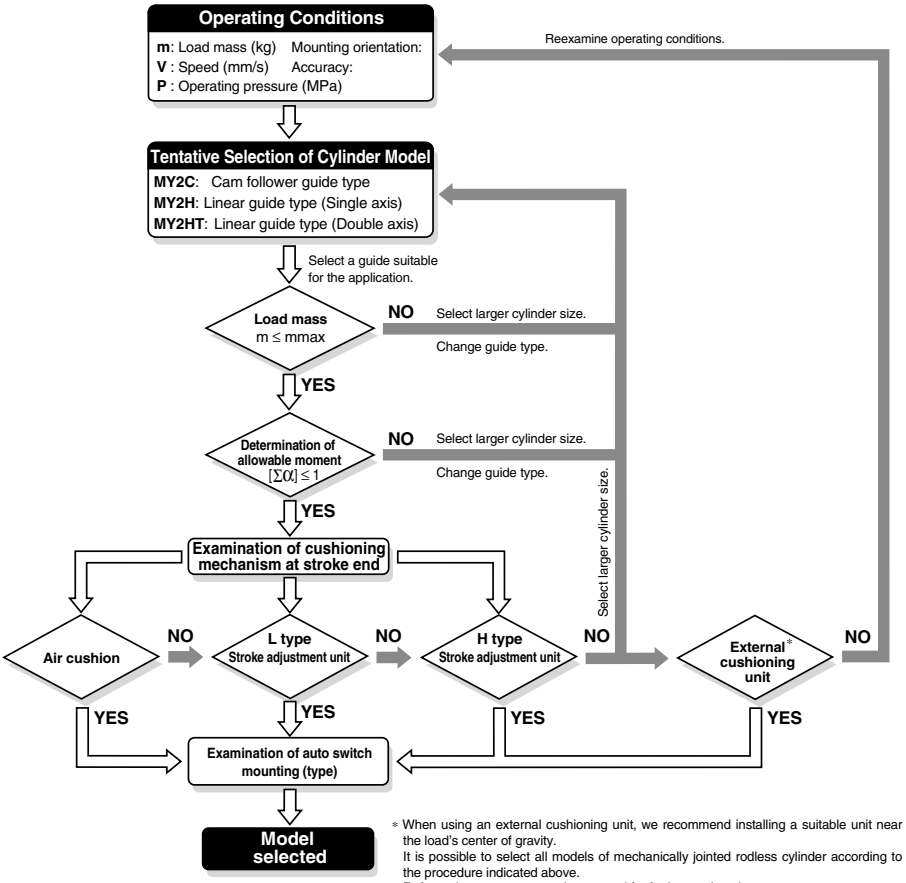
Standards for Tentative Model Selection

Cylinder model	Guide type	Standards for guide selection	Graphs for related allowable values
MY2C	Cam follower guide	Slide table accuracy approx. ±0.05 mm Note 2)	Refer to page 1089.
MY2H	Linear guide type (Single axis)	Slide table accuracy ±0.05 mm or less Note 2)	Refer to page 1090.
MY2HT	Linear guide type (Double axis)	Slide table accuracy ±0.05 mm or less Note 2)	Refer to page 1091.

Note 1) Please use the precision of each guide as a guideline for selection.
Note 2) Accuracy indicates displacement of the table (at stroke end) when 50% of the allowable moment shown in the catalog is applied. (Reference value)



Selection Flow Chart

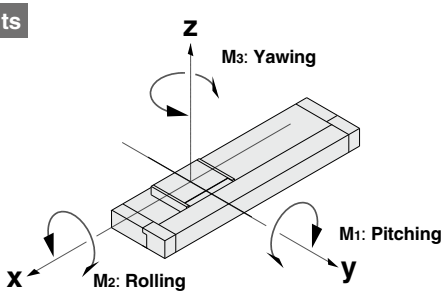


* When using an external cushioning unit, we recommend installing a suitable unit near the load's center of gravity.
It is possible to select all models of mechanically jointed rodless cylinder according to the procedure indicated above.
Refer to the separate operation manual for further explanation.

Types of Moment Applied on Rodless Cylinders

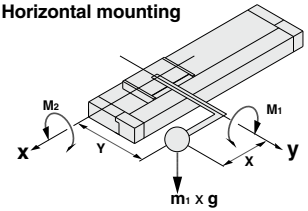
Multiple moments may be generated depending on the mounting orientation, load, and position of the center of gravity.

Coordinates and Moments

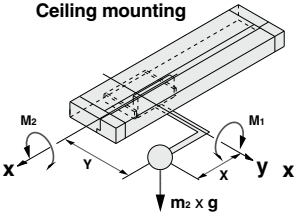


Static Moment

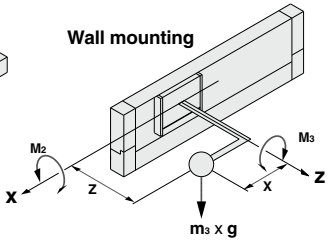
Horizontal mounting



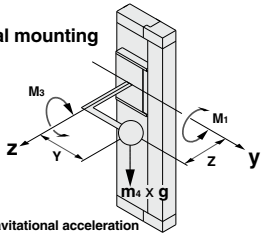
Ceiling mounting



Wall mounting



Vertical mounting

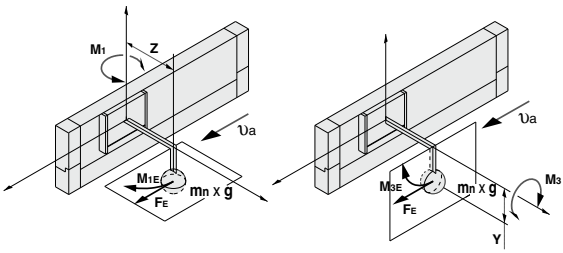


g: Gravitational acceleration

Mounting orientation		Horizontal	Ceiling	Wall	Vertical
Static load **m**		m_1	m_2	m_3	m_4 Note)
Static moment	M_1	$m_1 \times g \times X$	$m_2 \times g \times X$	——	$m_4 \times g \times Z$
	M_2	$m_1 \times g \times Y$	$m_2 \times g \times Y$	$m_3 \times g \times Z$	——
	M_3	——	——	$m_3 \times g \times X$	$m_4 \times g \times Y$

Note) m_4 is a mass movable by thrust. Use 0.3 to 0.7 times the thrust (differs depending on the operating speed) as a guide for actual use.

Dynamic Moment



g: Gravitational acceleration, υa: Average speed

Mounting orientation		Horizontal	Ceiling	Wall	Vertical
Dynamic load **FE**		$\frac{1.4}{100} \times \upsilon a \times m_n \times g$			
Dynamic moment	M_{1E}	$\frac{1}{3} \times F_E \times Z$			
	M_{2E}	**Dynamic moment M_{2E} does not occur.**			
	M_{3E}	$\frac{1}{3} \times F_E \times Y$			

Note) Regardless of the mounting orientation, dynamic moment is calculated with the formulas above.

Maximum Allowable Moment/Maximum Load Mass

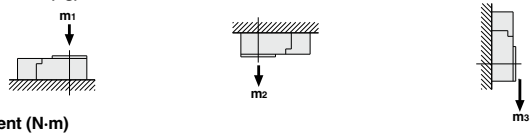
Model	Bore size (mm)	Maximum allowable moment (N·m)			Maximum load mass (kg)		
		M_1	M_2	M_3	m_1	m_2	m_3
MY2C	16	5	4	3.5	18	16	14
	25	13	14	10	35	35	30
	40	45	33	28	68	66	57
MY2H	16	7	6	7	15	13	13
	25	28	26	26	32	30	30
	40	60	50	60	62	62	62
MY2HT	16	46	55	46	20	18	18
	25	100	120	100	38	35	35
	40	200	220	200	80	80	80

The above values are the maximum allowable values for moment and load. Refer to each graph regarding the maximum allowable moment and maximum load mass for a particular piston speed.

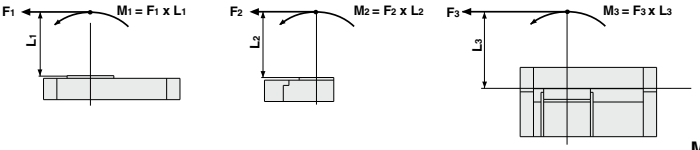
Caution on Design

If the product is operated with a guide load factor which exceeds the standard value, malfunction may occur due to damage to the cam follower and guide portion. Therefore, be sure to confirm that the guide load factor is 1 or less.

Load mass (kg)



Moment (N·m)



<Calculation of guide load factor>

1. Maximum load mass (1), static moment (2), and dynamic moment (3) (at the time of impact with stopper) must be examined for the selection calculations.

∗ To evaluate, use υa (average speed) for (1) and (2), and υ (impact speed $\upsilon = 1.4\upsilon a$) for (3).
Calculate m max for (1) from the maximum load mass graph (m_1, m_2, m_3) and Mmax for (2) and (3) from the maximum allowable moment graph (M_1, M_2, M_3).

$$\text{Sum of guide load factors } \Sigma\alpha = \frac{\text{Load mass [m]}}{\text{Maximum load mass [m max]}} + \frac{\text{Static moment [M]}^{(1)}}{\text{Allowable static moment [Mmax]}} + \frac{\text{Dynamic moment [M}_E\text{]}^{(2)}}{\text{Allowable dynamic moment [Memax]}} \leq 1$$

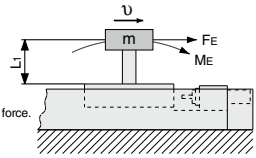
Note 1) Moment caused by the load, etc., with cylinder in resting condition.
Note 2) Moment caused by the impact load equivalent at the stroke end (at the time of impact with stopper).
Note 3) Depending on the shape of the workpiece, multiple moments may occur. When this happens, the sum of the load factors ($\Sigma\alpha$) is the total of all such moments.

2. Reference formulas [Dynamic moment at impact]
Use the following formulas to calculate dynamic moment when taking stopper impact into consideration.

- m : Load mass (kg)
- F : Load (N)
- F_E : Load equivalent to impact (at impact with stopper) (N)
- υa : Average speed (mm/s)
- M : Static moment (N·m)
- υ : Impact speed (mm/s)
- L_1 : Distance to the load's center of gravity (m)
- M_E : Dynamic moment (N·m)
- g : Gravitational acceleration (9.8 m/s^2)

$\upsilon = 1.4\upsilon a$ (mm/s) $\quad F_E = \frac{1.4}{100}\upsilon a \cdot g \cdot m$ Note 4)

$\therefore M_E = \frac{1}{3} \cdot F_E \cdot L_1 = 0.05\upsilon a \; m \; L_1$ (N·m) Note 5)



Note 4) $\frac{1.4}{100}\upsilon a$ is a dimensionless coefficient for calculating impact force.

Note 5) Average load coefficient (= $\frac{1}{3}$):
This coefficient is for averaging the maximum load moment at the time of stopper impact according to service life calculations.

3. Refer to pages 1094 and 1095 for detailed selection procedures.

Maximum Allowable Moment

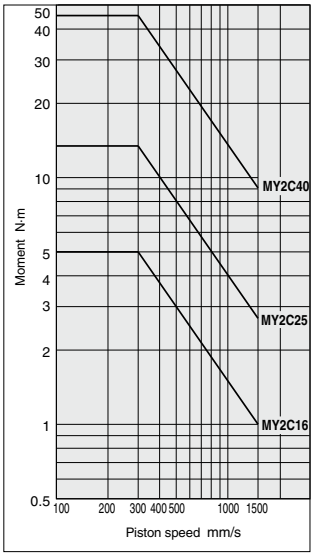
Select the moment from within the range of operating limits shown in the graphs. Note that the maximum load mass value may sometimes be exceeded even within the operating limits shown in the graphs. Therefore, also check the allowable load for the selected conditions.

Maximum Load Mass

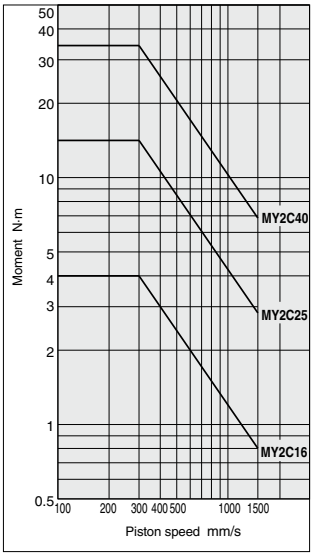
Select the load mass from within the range of limits shown in the graphs. Note that the maximum allowable moment value may sometimes be exceeded even within the operating limits shown in the graphs. Therefore, also check the allowable moment for the selected conditions.

Moment/MY2C

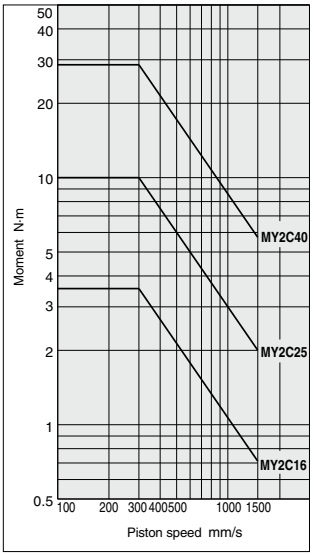
MY2C/M_1



MY2C/M_2

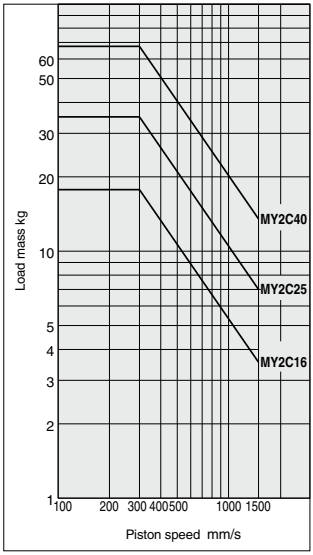


MY2C/M_3

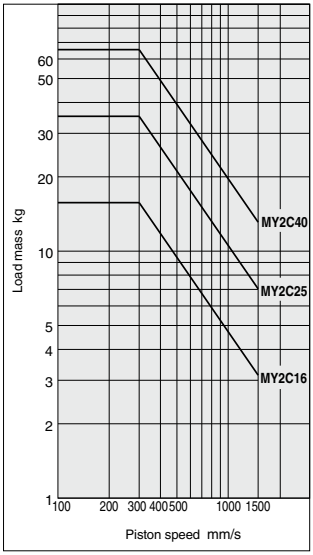


Load Mass/MY2C

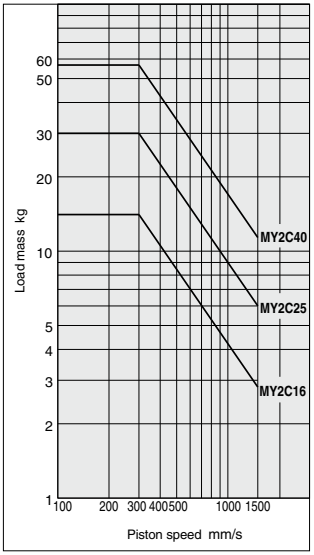
MY2C/m_1



MY2C/m_2



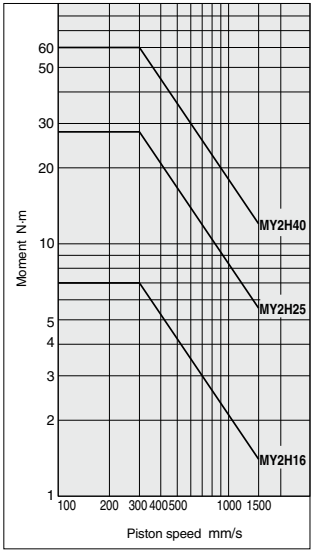
MY2C/m_3



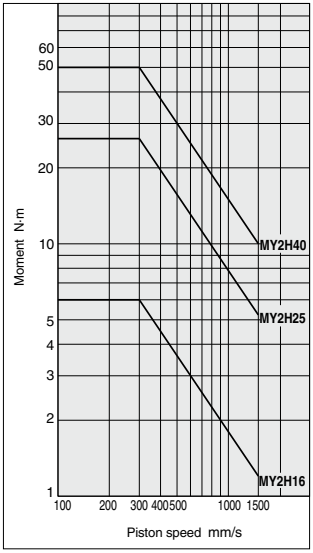
Maximum Allowable Moment/Maximum Load Mass

Moment/MY2H (Single axis)

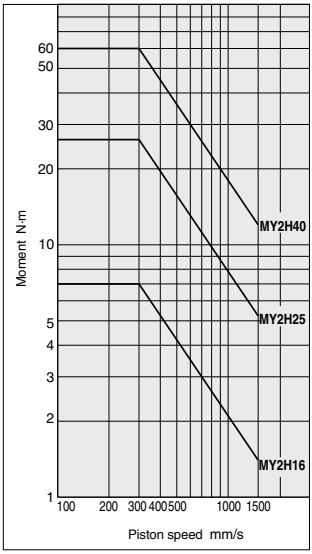
MY2H/M1



MY2H/M2

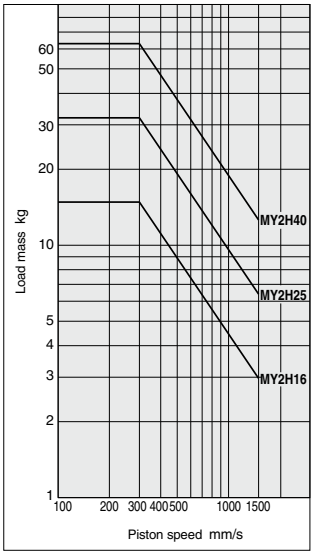


MY2H/M3

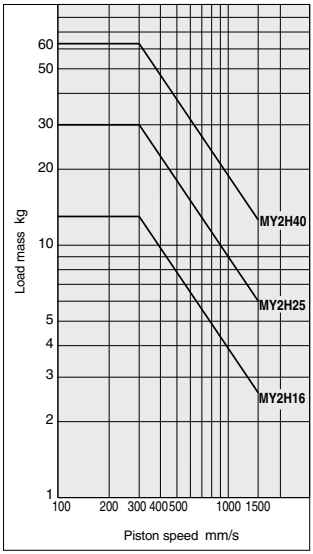


Load Mass/MY2H (Single axis)

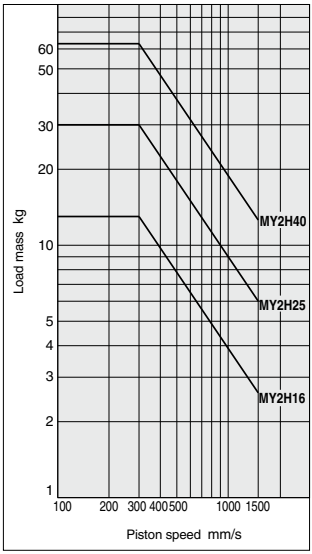
MY2H/m1



MY2H/m2

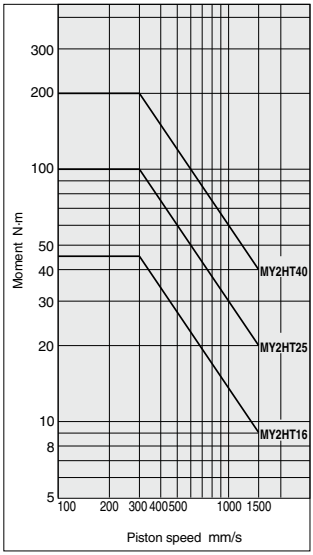


MY2H/m3

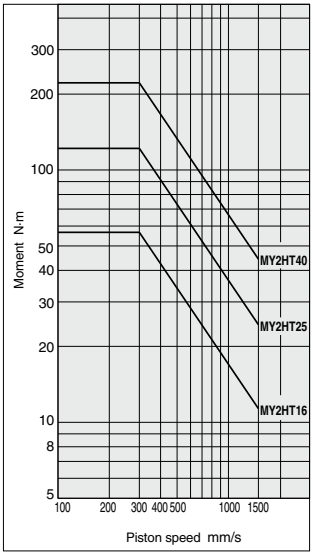


Moment/MY2HT (Double axis)

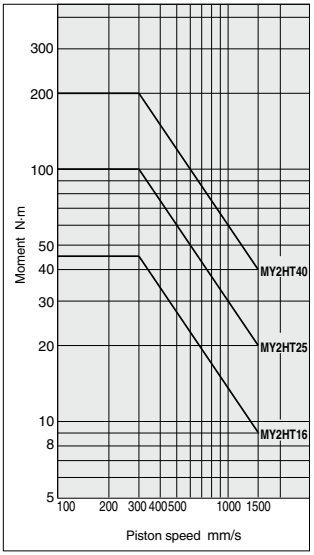
MY2HT/M1



MY2HT/M2

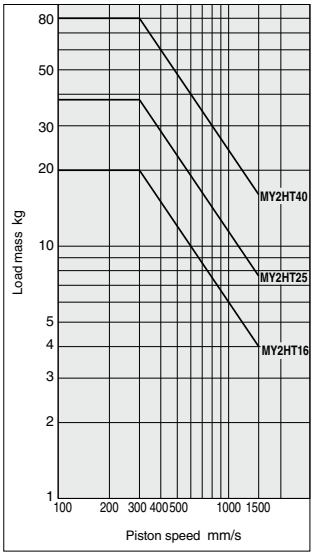


MY2HT/M3

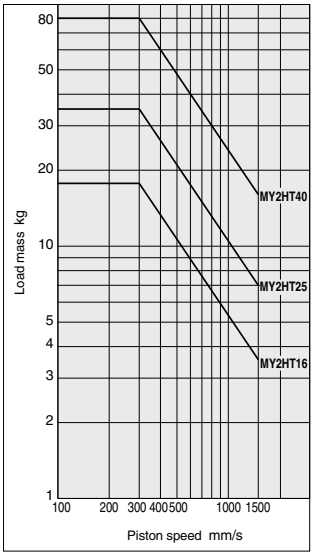


Load Mass/MY2HT (Double axis)

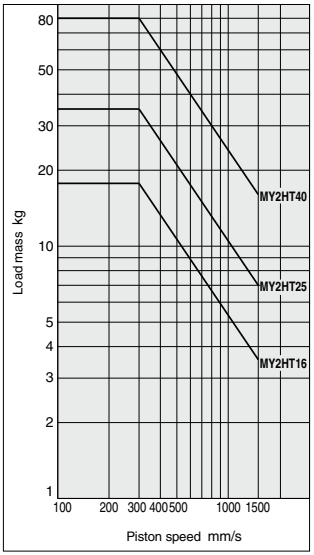
MY2HT/m1



MY2HT/m2



MY2HT/m3



Cushion Capacity

Cushion Selection

<Air cushion>
Air cushions are a standard feature on mechanically jointed rodless cylinders.
The air cushion mechanism is installed to avoid excessive impact of the piston at the stroke end during high speed operation. The air cushion does not act to decelerate the piston near the stroke end.
The ranges of load and speed that air cushions can absorb are within the air cushion limit lines shown in the graphs.

<Stroke adjustment unit with shock absorber>
Use this unit when operating with a load or speed exceeding the air cushion limit line, or when cushioning is necessary because the cylinder stroke is outside of the effective air cushion stroke range due to stroke adjustment.

L unit
Use this unit when cushioning is necessary outside of the effective air cushion range even if the load and speed are within the air cushion limit line, or when the cylinder is operated in a load and speed range above the air cushion limit line and below the L unit limit line.

H unit
Use this unit when the cylinder is operated in a load and speed range above the L unit limit line and below the H unit limit line.

⚠Caution

Do not use a shock absorber and air cushion together.

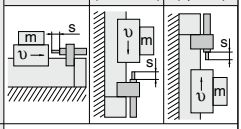
Air Cushion Stroke (mm)

Bore size (mm)	Cushion stroke
16	12
25	15
40	24

Stroke Adjustment Unit Holding Bolt Tightening Torque (N·m)

Bore size (mm)	Tightening torque
16	0.7
25	1.8
40	5.8

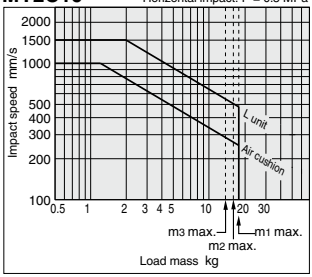
Calculation of Absorbed Energy for Stroke Adjustment Unit with Shock Absorber (N·m)

	Horizontal	Vertical (downward)	Vertical (upward)
Type of impact			
Kinetic energy **E1**	$\frac{1}{2}\,m \cdot \upsilon^2$		
Thrust energy **E2**	$F \cdot s$	$F \cdot s + m \cdot g \cdot s$	$F \cdot s - m \cdot g \cdot s$
Absorbed energy **E**	$E_1 + E_2$		

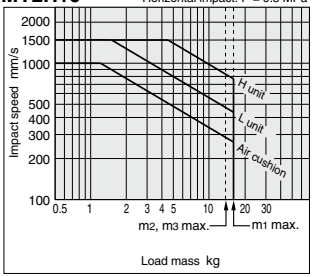
Symbols
υ: Speed of impacting object (m/s) m: Mass of impacting object (kg)
F: Cylinder thrust (N) g: Gravitational acceleration (9.8 m/s²)
s: Shock absorber stroke (m)
Note) The speed of the impacting object is measured at the time of impact with the shock absorber.

Absorption Capacity of Air Cushion and Stroke Adjustment Units

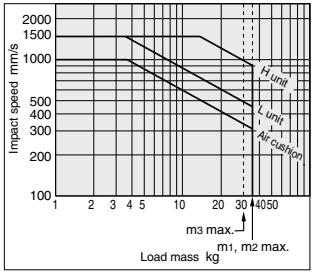
MY2C16 Horizontal impact: P = 0.5 MPa



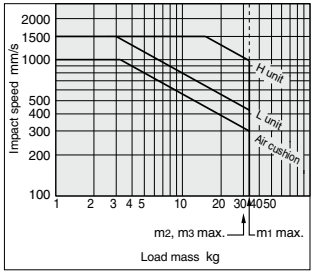
MY2H16 Horizontal impact: P = 0.5 MPa



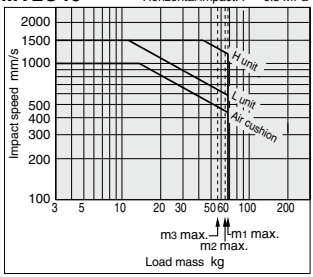
MY2C25 Horizontal impact: P = 0.5 MPa



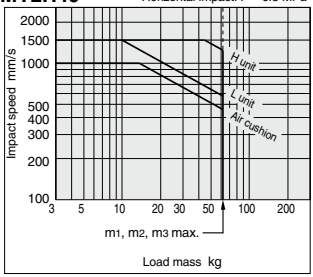
MY2H25 Horizontal impact: P = 0.5 MPa



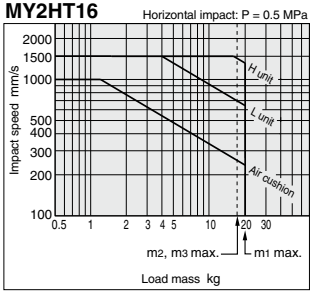
MY2C40 Horizontal impact: P = 0.5 MPa



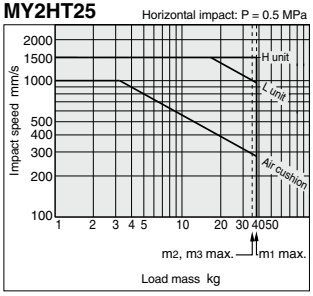
MY2H40 Horizontal impact: P = 0.5 MPa



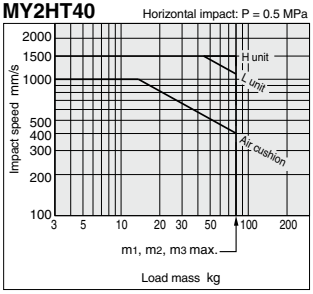
MY2HT16



MY2HT25



MY2HT40



⚠ Specific Product Precautions

Be sure to read this before handling the products. Refer to page 8 for safety instructions and pages 9 to 18 for actuator and auto switch precautions.

Handling

⚠ Caution

1. Do not get your hands caught during cylinder operation.

For the cylinder with a stroke adjustment unit, the space between the slide table and stroke adjustment unit is very small, and your hands may get caught. When operating without a protective cover, be careful not to get your hands caught.

2. Do not operate with the stroke adjustment unit fixed in an intermediate position.

When the stroke adjustment unit is fixed in an intermediate position, slippage can occur depending on the amount of energy released at the time of an impact. In such cases, as a stroke adjustment unit with the spacer for intermediate securing is available, it is recommended to use it.

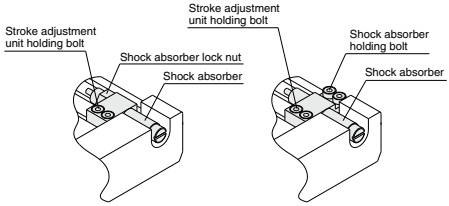
<Securing the unit body>

The unit body is secured by equally tightening the two stroke adjustment unit holding bolts. (See drawings below.)

<Stroke adjustment of shock absorber>

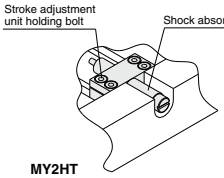
For MY2C and MY2H

Loosen the shock absorber lock nut (shock absorber holding bolts for MY2H16, H unit), and adjust the stroke by rotating the shock absorber. After the adjustment, tighten the lock nut (holding bolts) to secure the shock absorber.



For MY2HT

Loosen the two unit holding bolts on the shock absorber side, rotate the shock absorber and adjust the stroke. After the adjustment, secure the shock absorber by tightening the unit holding bolts equally.



Tightening torque for stroke adjustment unit holding bolts N·m

Bore size (mm)	Tightening torque
16	0.7
25	1.8
40	5.8

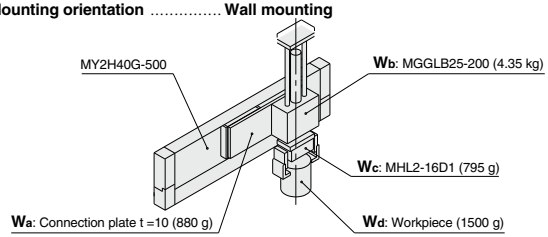
Model Selection 2

The following are the steps for selection of the MY2 series best suited to your application.

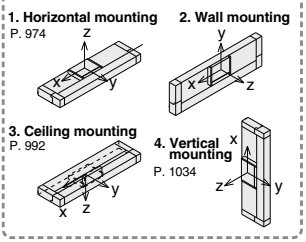
Calculation of Guide Load Factor

1 Operating Conditions

Cylinder **MY2H40G-500**
Average operating speed υa ... **300 mm/s**
Mounting orientation ..... **Wall mounting**

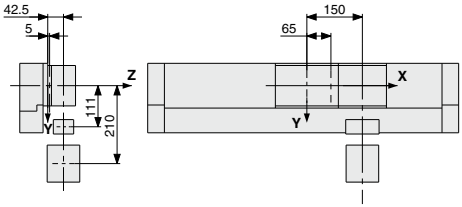


Mounting Orientation



Refer to the pages above for actual examples of calculation for each orientation.

2 Load Blocking



Workpiece Mass and Center of Gravity

Workpiece no. **Wn**	Mass **mn**	Center of gravity		
		X-axis **Xn**	Y-axis **Yn**	Z-axis **Zn**
Wa	0.88 kg	65 mm	0 mm	5 mm
Wb	4.35 kg	150 mm	0 mm	42.5 mm
Wc	0.795 kg	150 mm	111 mm	42.5 mm
Wd	1.5 kg	150 mm	210 mm	42.5 mm

n = a, b, c, d

3 Composite Center of Gravity Calculation

$\mathbf{m_3} = \Sigma \mathbf{m_n}$
$= 0.88 + 4.35 + 0.795 + 1.5 = \mathbf{7.525\ kg}$

$\mathbf{X} = \frac{1}{\mathbf{m_3}} \times \Sigma\ (\mathbf{m_n} \times \mathbf{x_n})$
$= \frac{1}{7.525}\ (0.88 \times 65 + 4.35 \times 150 + 0.795 \times 150 + 1.5 \times 150) = \mathbf{140.1\ mm}$

$\mathbf{Y} = \frac{1}{\mathbf{m_3}} \times \Sigma\ (\mathbf{m_n} \times \mathbf{y_n})$
$= \frac{1}{7.525}\ (0.88 \times 0 + 4.35 \times 0 + 0.795 \times 111 + 1.5 \times 210) = \mathbf{53.6\ mm}$

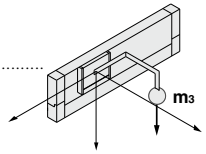
$\mathbf{Z} = \frac{1}{\mathbf{m_3}} \times \Sigma\ (\mathbf{m_n} \times \mathbf{z_n})$
$= \frac{1}{7.525}\ (0.88 \times 5 + 4.35 \times 42.5 + 0.795 \times 42.5 + 1.5 \times 42.5) = \mathbf{38.1\ mm}$

4 Calculation of Load Factor for Static Load

m_3: Mass

m_3 max (from 1 of graph MY2H/**m_3**) = 62 (kg) .....

Load factor α_1 = **m_3** /**m_3 max** = 7.525/62 = **0.12**

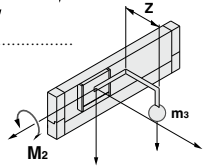


M_2: Moment

M_2 max (from 2 of graph MY2H/**M_2**) = 50 (N·m) .....

$M_2 = m_3 \times g \times Z = 7.525 \times 9.8 \times 38.1 \times 10^{-3} = 2.81$ (N·m)

Load factor α_2 = **M_2**/**M_2 max** = 2.81/50 = **0.06**



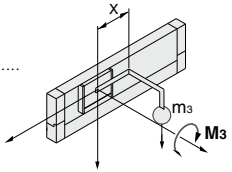
Calculation of Guide Load Factor

M_3: Moment

M_3 max (from 3 of graph MY2H/**M_3**) = 60 (N·m) .....

$M_3 = m_3 \times g \times X = 7.525 \times 9.8 \times 140.1 \times 10^{-3} = 10.33$ (N·m)

Load factor α_3 = M_3/M_3 **max** = 10.33/60 = **0.17**



5 Calculation of Load Factor for Dynamic Moment

Equivalent load F_E at impact

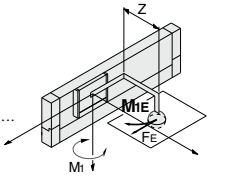
$F_E = \frac{1.4}{100} \times \upsilon a \times g \times m = \frac{1.4}{100} \times 300 \times 9.8 \times 7.525 = 309.7$ (N)

M_{1E}: Moment

M_{1E} max (from 4 of graph MY2H/**M_1** where $1.4\upsilon a$ = 420 mm/s) = 42.9 (N·m) .....

$M_{1E} = \frac{1}{3} \times F_E \times Z = \frac{1}{3} \times 309.7 \times 38.1 \times 10^{-3} = 3.93$ (N·m)

Load factor α_4 = M_{1E}/M_{1E} **max** = 3.93/42.9 = **0.09**

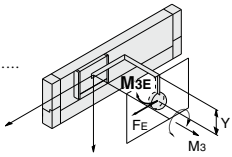


M_{3E}: Moment

M_{3E} max (from 5 of graph MY2H/**M_3** where $1.4\upsilon a$ = 420 mm/s) = 42.9 (N·m) .....

$M_{3E} = \frac{1}{3} \times F_E \times Y = \frac{1}{3} \times 309.7 \times 53.6 \times 10^{-3} = 5.53$ (N·m)

Load factor α_5 = M_{3E}/M_{3E} **max** = 5.53/42.9 = **0.13**

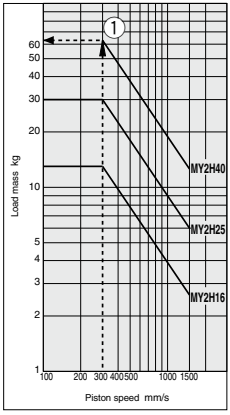


6 Sum and Examination of Guide Load Factors

$\Sigma\alpha = \alpha_1 + \alpha_2 + \alpha_3 + \alpha_4 + \alpha_5$ = **0.57** ≤ **1**

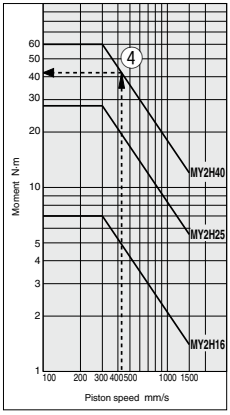
Load Mass

MY2H/m_3

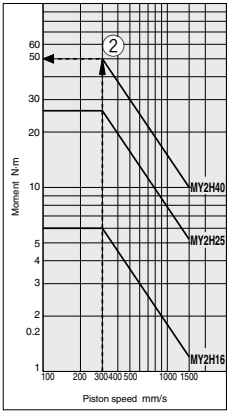


Allowable Moment

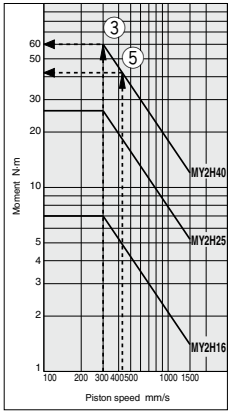
MY2H/M_1



MY2H/M_2



MY2H/M_3



Mechanically Jointed Rodless Cylinder
Cam Follower Guide Type
MY2C Series
ø16, ø25, ø40

How to Order

Cam Follower Guide Type **MY2C 16 ☐ G – 300 ☐ – M9BW ☐ – ☐**

Guide type

C	Cam follower guide

Bore size

16	16 mm
25	25 mm
40	40 mm

Port thread type

Symbol	Type	Bore size
Nil	M thread	ø16
	Rc	ø25, ø40
TN	NPT	
TF	G	

Piping

G	Centralized piping type (Standard)

Cylinder stroke (mm)

Bore size	Standard stroke*1	Long stroke	Maximum manufacturable stroke
16	100, 200, 300, 400, 500, 600 700, 800, 900, 1000, 1200 1400, 1600, 1800, 2000	Strokes of 2001 to 3000 mm (1 mm increments) exceeding the standard stroke	3000
25, 40	*1 The stroke can be manufactured in 1 mm increments from 1 mm stroke.	Strokes of 2001 to 5000 mm (1 mm increments) exceeding the standard stroke	5000

Ordering example
* Long stroke can be ordered the same as the standard stroke. MY2C25-3000L-M9BW

Note) Please be advised that with stroke 49 or less, there are cases where auto switch mounting is not possible and the performance of the air cushion may decline.

Stroke adjustment unit symbol
Refer to "Stroke adjustment unit" on page 1097.

Auto switch

Nil	Without auto switch (Built-in magnet)

* Refer to the table below for the applicable auto switch model.

Number of auto switches

Nil	2 pcs.
S	1 pc.
n	"n" pcs.

Made to Order
Refer to page 1097 for details.

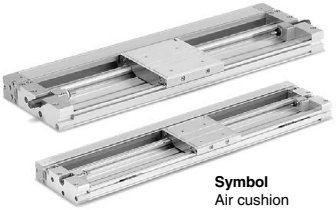
Applicable Auto Switches/Refer to pages 1289 to 1383 for further information on auto switches.

Type	Special function	Electrical entry	Indicator light	Wiring (Output)	Load voltage DC	Load voltage AC	Auto switch model Perpendicular	Auto switch model In-line	Lead wire length (m) 0.5 (Nil)	1 (M)	3 (L)	5 (Z)	Pre-wired connector	Applicable load	
Solid state auto switch	——	Grommet	Yes	3-wire (NPN)	5 V, 12 V	—	**M9NV**	**M9N**	●	●	●	○	○	IC circuit	Relay, PLC
				3-wire (PNP)			**M9PV**	**M9P**	●	●	●	○	○		
				2-wire	12 V		**M9BV**	**M9B**	●	●	●	○	○	—	
	Diagnostic indication (2-color indicator)			3-wire (NPN)	5 V, 12 V		**M9NWV**	**M9NW**	●	●	●	○	○	IC circuit	
				3-wire (PNP)			**M9PWV**	**M9PW**	●	●	●	○	○		
				2-wire	12 V		**M9BWV**	**M9BW**	●	●	●	○	○	—	
	Water resistant (2-color indicator)			3-wire (NPN)	5 V, 12 V		**M9NAV***1	**M9NA***1	○	○	●	○	○	IC circuit	
				3-wire (PNP)			**M9PAV***1	**M9PA***1	○	○	●	○	○		
				2-wire	12 V		**M9BAV***1	**M9BA***1	○	○	●	○	○	—	
Reed auto switch	——	Grommet	Yes	3-wire (NPN equivalent)	—	5 V	—	**A96V**	**A96**	●	—	●	—	—	IC circuit	—
			No	2-wire	24 V	12 V	100 V	**A93V***2	**A93**	●	●	●	●	—	—	Relay, PLC
							100 V or less	**A90V**	**A90**	●	—	●	—	—	IC circuit	

* Lead wire length symbols: 0.5 m ····· Nil (Example) M9NW
1 m ····· M (Example) M9NWM
3 m ····· L (Example) M9NWL
5 m ····· Z (Example) M9NWZ

* Solid state auto switches marked with "○" are produced upon receipt of order.

* There are other applicable auto switches than listed above. For details, refer to page 1114.
* For details about auto switches with pre-wired connector, refer to pages 1358 and 1359.
* Auto switches are shipped together (not assembled). (Refer to page 1114 for the details of auto switch mounting.)



Symbol
Air cushion
(Carrier piston type)

Made to Order

Made to Order: Individual Specifications
(For details, refer to page 1115.)

Symbol	Specifications
-X168	Helical insert thread

Made to Order Specifications
Click here for details

Symbol	Specifications
-XB22	Shock absorber soft type RJ series type

Specifications

Bore size (mm)	16	25	40
Fluid	Air		
Action	Double acting		
Operating pressure range	0.15 to 0.8 MPa	0.1 to 0.8 MPa	
Proof pressure	1.2 MPa		
Ambient and fluid temperature	5 to 60°C		
Cushion	Air cushion, Shock absorber		
Lubrication	Not required (Non-lube)		
Stroke length tolerance	1000 or less $^{+1.8}_{0}$ 1001 to 3000 $^{+2.8}_{0}$	2700 or less $^{+1.8}_{0}$, 2701 to 5000 $^{+2.8}_{0}$	
Port size	M5 x 0.8	Rc 1/8	Rc 1/4

Piston Speed

Bore size (mm)		16	25	40
Without stroke adjustment unit		100 to 1000 mm/s(1)		
Stroke adjustment unit	**L unit and H unit**	100 to 1500 mm/s		

Note 1) When exceeding the air cushion stroke ranges on page 1092, the **piston speed** should be **100 to 200 mm/s.**
Note 2) Use at a piston speed within the absorption capacity range. Refer to page 1092.

Stroke Adjustment Unit Specifications

Bore size (mm)		16	25		40	
Unit symbol		L	L	H	L	H
Shock absorber model		RB0806	RB1007	RB1412	RB1412	RB2015
Stroke adjustment range by intermediate fixing spacer (mm)	**Without spacer**	0 to –5.6	0 to –11.5		0 to –16	
	With short spacer	–5.6 to –11.2	–11.5 to –23		–16 to –32	
	With long spacer	–11.2 to –16.8	–23 to –34.5		–32 to –48	

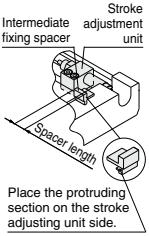
∗ Stroke adjustment range is applicable for one side when mounted on a cylinder.

Stroke Adjustment Unit Symbol

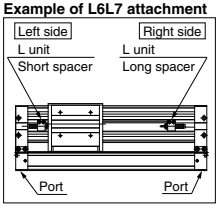
Left side stroke adjustment unit		Right side stroke adjustment unit: Without unit	L: With low load shock absorber			H: With high load shock absorber		
				With short spacer	With long spacer		With short spacer	With long spacer
Without unit		**Nil**	**SL**	**SL6**	**SL7**	**SH**	**SH6**	**SH7**
L: With low load shock absorber		**LS**	**L**	**LL6**	**LL7**	**LH**	**LH6**	**LH7**
	With short spacer	**L6S**	**L6L**	**L6**	**L6L7**	**L6H**	**L6H6**	**L6H7**
	With long spacer	**L7S**	**L7L**	**L7L6**	**L7**	**L7H**	**L7H6**	**L7H7**
H: With high load shock absorber		**HS**	**HL**	**HL6**	**HL7**	**H**	**HH6**	**HH7**
	With short spacer	**H6S**	**H6L**	**H6L6**	**H6L7**	**H6H**	**H6**	**H6H7**
	With long spacer	**H7S**	**H7L**	**H7L6**	**H7L7**	**H7H**	**H7H6**	**H7**

∗ Spacers are used to fix the stroke adjustment unit at an intermediate stroke position.

Stroke adjustment unit mounting diagram



Example of L6L7 attachment



Shock Absorbers for L and H Units

Type	Stroke adjustment unit	Bore size (mm) 16	25	40
Standard (Shock absorber/RB series)	L	RB0806	RB1007	RB1412
	H	—	RB1412	RB2015
Shock absorber/soft type RJ series mounted (-XB22)	L	RJ0806H	RJ1007H	RJ1412H
	H	—	RJ1412H	—

∗ The shock absorber service life is different from that of the MY2C cylinder depending on operating conditions. Refer to the RB Series Specific Product Precautions for the replacement period.
∗ Mounted shock absorber soft type RJ series (-XB22) is made to order specifications. For details, refer to page 1468.

Shock Absorber Specifications

Model		RB 0806	RB 1007	RB 1412	RB 2015
Max. energy absorption (J)		2.9	5.9	19.6	58.8
Stroke absorption (mm)		6	7	12	15
Max. collision speed (mm/s)		1500	1500	1500	1500
Max. operating frequency (cycle/min)		80	70	45	25
Spring force (N)	**Extended**	1.96	4.22	6.86	8.34
	Retracted	4.22	6.86	15.98	20.50
Operating temperature range (°C)		5 to 60			

∗ The shock absorber service life is different from that of the MY2C cylinder depending on operating conditions. Refer to the RB Series Specific Product Precautions for the replacement period.

Theoretical Output

(N)

Bore size (mm)	Piston area (mm^2)	Operating pressure (MPa)						
		0.2	0.3	0.4	0.5	0.6	0.7	0.8
16	200	40	60	80	100	120	140	160
25	490	98	147	196	245	294	343	392
40	1256	251	377	502	628	754	879	1005

Note) Theoretical output (N) = Pressure (MPa) x Piston area (mm^2)

Weight

(kg)

Bore size (mm)	Basic weight	Additional weight per each 50 mm of stroke	Weight of moving parts	Side support bracket weight (per set)	Stroke adjustment unit weight (per unit)	
					L unit weight	H unit weight
16	1.05	0.13	0.34	0.01	0.03	—
25	2.59	0.29	0.97	0.02	0.06	0.09
40	8.78	0.67	3.09	0.04	0.17	0.23

Calculation: (Example) **MY2C25G-300L**
- Basic weight ..... 2.59 kg
- Cylinder stroke ..... 300 stroke
- Additional weight ..... 0.29/50 stroke

2.59 + 0.29 x 300/50 + 0.06 x 2 ≅ 4.45 kg
- Weight of L unit ..... 0.06 kg

Replacement Parts

Drive Unit (Cylinder) Replacement Part No.

Model / Bore size (mm)	**MY2C**
16	MY2BH16G- Stroke
25	MY2BH25□G- Stroke
40	MY2BH40□G- Stroke

Enter a symbol for port thread type inside □.
Note) Order auto switches separately.

Option

Stroke Adjustment Unit Part No.

MY2C − A 25 L2 − 6N

Stroke adjustment unit

Bore size

16	16 mm
25	25 mm
40	40 mm

Unit no.

Symbol	Stroke adjustment unit	Mounting position
L1	L unit	Left
L2		Right
H1	H unit	Left
H2		Right

Note 1) Refer to page 1097 for details about adjustment range.
Note 2) L unit only for ø16

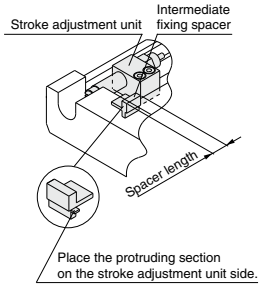
Intermediate fixing spacer

Nil	Without spacer
6□	Short spacer
7□	Long spacer

Spacer delivery type

Nil	Unit installed
N	Spacer only

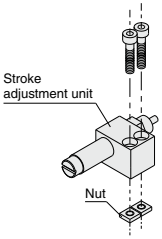
∗ Spacers are used to fix the stroke adjustment unit at an intermediate stroke position.
∗ Spacers are shipped for a set of two.



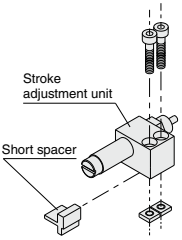
∗ When ordering the intermediate fixing spacer for the stroke adjustment unit, the intermediate fixing spacer is shipped together.

Component Parts

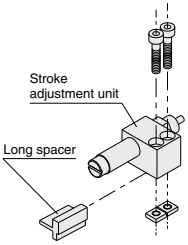
MY2C-A25L2 (Without spacer)



MY2C-A25L2-6 (With short spacer)



MY2C-A25L2-7 (With long spacer)



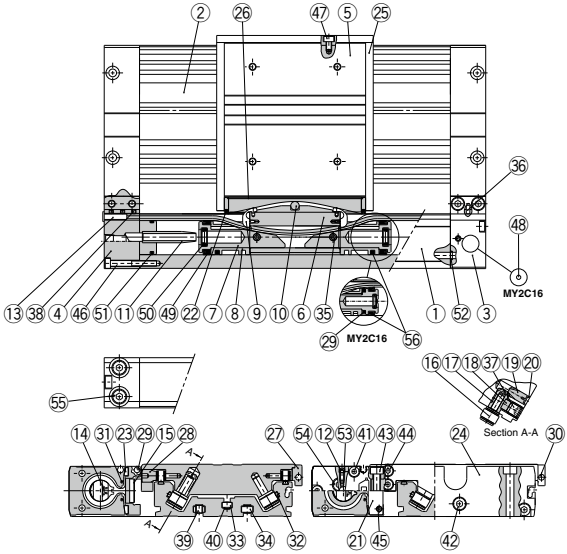
MY2C-A25L2-6N (Short spacer only)

MY2C-A25L2-7N (Long spacer only)

∗ Nuts are equipped on the cylinder body.

Construction

MY2C



Component Parts

No.	Description	Material	Note
1	**Cylinder tube**	Aluminium alloy	Hard anodized
2	**Body**	Aluminium alloy	Hard anodized
3	**Head cover WR**	Aluminium alloy	Hard anodized
4	**Head cover WL**	Aluminium alloy	Hard anodized
5	**Slide table**	Aluminium alloy	Hard anodized
6	**Piston yoke**	Aluminium alloy	Hard anodized
7	**Piston**	Aluminium alloy	Chromated
8	**Wear ring**	Special resin	
9	**Belt separator**	Special resin	
10	**Parallel pin**	Stainless steel	
11	**Cushion ring**	Aluminum alloy	Anodized
12	**Cushion needle**	Rolled steel	Nickel plated
13	**Belt clamp**	Special resin	
16	**Cam follower**	—	
17	**Eccentric gear**	Stainless steel	
18	**Gear fixture**	Stainless steel	
19	**Adjustment gear**	Stainless steel	
20	**Retaining ring**	Stainless steel	
21	**End cover**	Aluminium alloy	Hard anodized
23	**Bearing**	Special resin	
24	**End plate**	Aluminium alloy	Hard anodized
25	**Stopper**	Carbon steel	Nickel plated after quenching
26	**Top cover**	Stainless steel	
27	**Side cover**	Aluminium alloy	Hard anodized

No.	Description	Material	Note
28	**Cam follower cap**	Aluminium alloy	Hard anodized
29	**Magnet**	—	
30	**Magnet**	—	
31	**Seal magnet**	Rubber magnet	
32	**Rail**	Hard steel wire material	
33	**Square nut**	Carbon steel	Chromated
34	**Square nut**	Carbon steel	Chromated
35	**Spring pin**	Carbon tool steel	
36	**Parallel pin**	Stainless steel	
37	**Hexagon socket set screw**	Chrome molybdenum steel	Black zinc chromated
38	**Hexagon socket set screw**	Chrome molybdenum steel	Black zinc chromated
39	**Hexagon socket set screw**	Chrome molybdenum steel	Chromated
40	**Hexagon socket set screw**	Chrome molybdenum steel	Chromated
41	**Hexagon socket head cap screw**	Chrome molybdenum steel	Chromated
42	**Hexagon socket head cap screw**	Chrome molybdenum steel	Chromated
43	**Hexagon socket head cap screw**	Chrome molybdenum steel	Chromated
44	**Hexagon socket head cap screw**	Chrome molybdenum steel	Chromated
45	**Hexagon socket head cap screw**	Chrome molybdenum steel	Chromated
46	**Hexagon socket head cap screw**	Chrome molybdenum steel	Chromated
47	**Hexagon socket head cap screw**	Chrome molybdenum steel	Chromated
48	**Steel ball**	Spring steel	Nickel plated
54	**Hexagon socket head (taper) plug**	Carbon steel	Chromated
55	**Hexagon socket head (taper) plug**	Carbon steel	Chromated
56	**Lube retainer**	Special resin	

Replacement Parts: Seal Kit

No.	Description	Qty.	MY2C16G	MY2C25G	MY2C40G
14	**Seal belt**	1	MY16-16C-Stroke	MY25-16C-Stroke	MY40-16C-Stroke
15	**Dust seal band**	1	MY2H16-16B-Stroke	MY2H25-16B-Stroke	MY2H40-16B-Stroke
53	**O-ring**	2	KA00309 (ø4 x ø1.8 x ø1.1)	KA00309 (ø4 x ø1.8 x ø1.1)	KA00320 (ø7.15 x ø3.75 x ø1.7)
22	**Scraper**	2	MY2B16-PS	MY2B25-PS	MY2B40-PS
49	**Piston seal**	2			
50	**Cushion seal**	2			
51	**Tube gasket**	2			
52	**O-ring**	4			

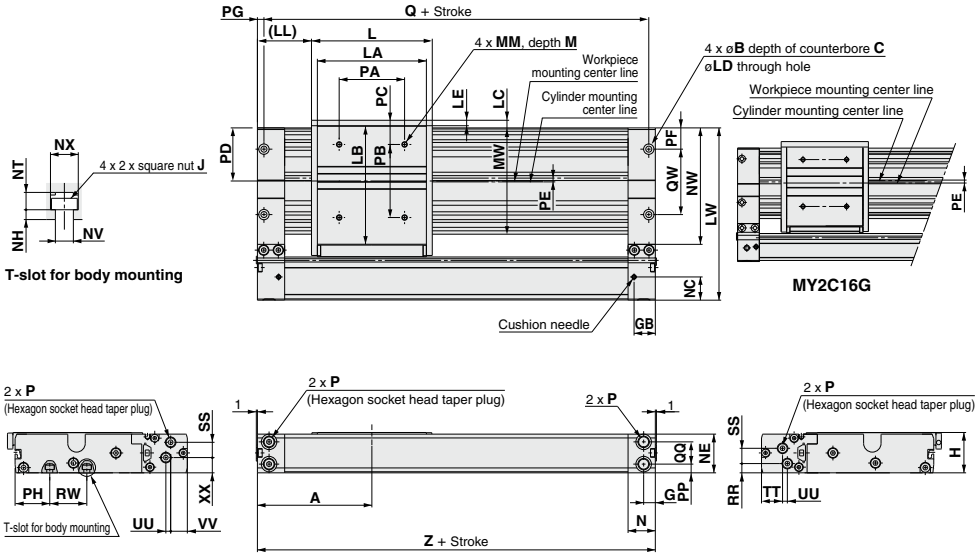
* Seal kit includes 22, 49, 50, 51 and 52. Order the seal kit based on each bore size.

* Seal kit includes a grease pack (10 g).
When 14 and 15 are shipped as single units, a grease pack (10 g per 1000 strokes) is included.
Order with the following part number when only the grease pack is needed.
Grease pack part number:GR-S-010 (10 g) **, GR-S-020** (20 g)

ø16, ø25, ø40

Refer to page 1118 regarding port variations.

MY2C Bore size **G** – Stroke



(mm)

Model	A	B	C	G	GB	H	L	J	LA	LB	LC	LD	LE	(LL)	LW	M	MM	MW	N	NC	NE	NH	NT
MY2C16G	80	6.5	3.3	8.5	17	28	80	M3 x 0.5	70	72.4	6	3.4	5	40	104	7	M4 x 0.7	64.6	20	14	27	2	3.5
MY2C25G	105	9.5	5.4	10.7	19.5	37	110.8	M5 x 0.8	100	108.7	7	5.5	5	49.6	158	9	M5 x 0.8	97.5	25	21.3	35.5	3	5.3
MY2C40G	165	14	8.6	15.5	31.5	58	180	M6 x 1	158	135.3	7	9	5	75	214	13	M6 x 1	121.5	40	32.4	56.5	4	6.5

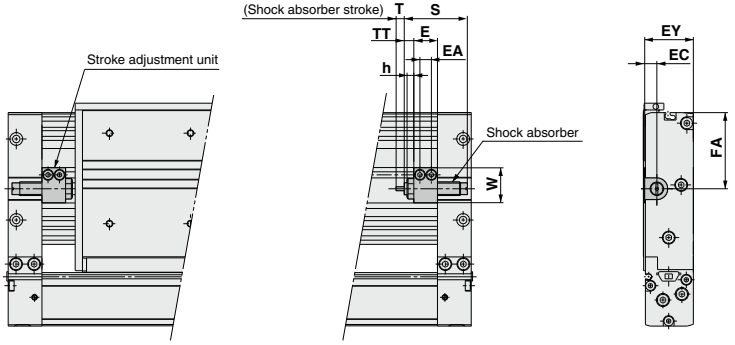
Model	NV	NW	NX	P	PA	PB	PC	PD	PE	PF	PG	PH	PP	Q	QQ	QW	RR	RW	SS	TT	UU	VV	XX	Z
MY2C16G	3.4	69.2	5.8	M5 x 0.8	40	43	16.5	32	2.2	9.8	4	21.3	5.3	152	16.4	40	5.3	22	9.7	12.5	3	10.5	12	160
MY2C25G	5.5	106.8	8.5	$^1/_8$	60	67	22.2	48.7	0.8	19.5	6	31.8	8	198	20.4	60	8.5	34	14	19.3	4.4	15.3	14	210
MY2C40G	6.6	135.1	10.5	$^1/_4$	100	77	29	60.5	8.5	40.5	9	38	16	312	25.5	57	11	45	21.5	35.4	2	29	23	330

"P" indicates cylinder supply ports. * The plug for "P" MY2C16G is a hexagon socket head plug.

Stroke adjustment unit

Low load shock absorber

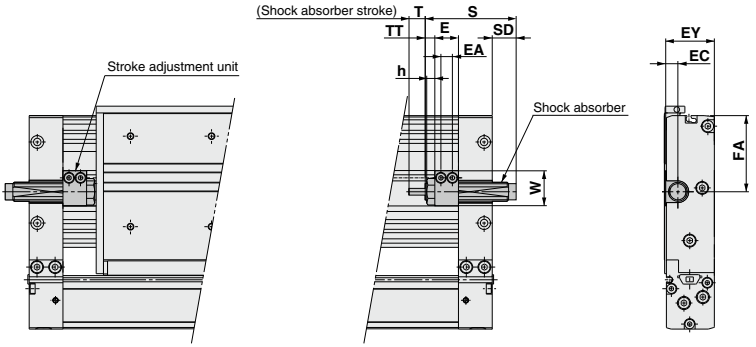
MY2C [Bore size] G – [Stroke] L



Applicable cylinder	E	EA	EC	EY	FA	h	S	T	TT	W	Shock absorber model
MY2C16	14.4	7	6	27	38.5	4	40.8	6	5.6 (Max. 11.2)	16.5	RB0806
MY2C25	17.5	8.5	9	36	56.4	5	46.7	7	7.1 (Max. 18.6)	25.8	RB1007
MY2C40	25	13	13.5	56.5	67.8	6	67.3	12	10 (Max. 26)	38	RB1412

High load shock absorber

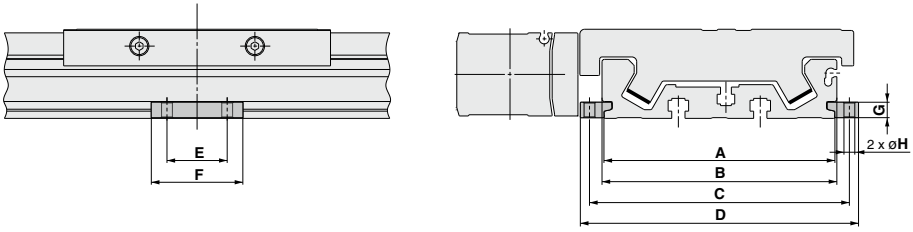
MY2C [Bore size] G – [Stroke] H



Applicable cylinder	E	EA	EC	EY	FA	h	S	SD	T	TT	W	Shock absorber model
MY2H25	17.5	8.5	9	36	56.4	6	67.3	17.7	12	7.1 (Max. 18.6)	25.8	RB1412
MY2H40	25	13	13.5	56.5	67.8	6	73.2	—	15	10 (Max. 26)	38	RB2015

Side Support

Side support
MYC-S□A

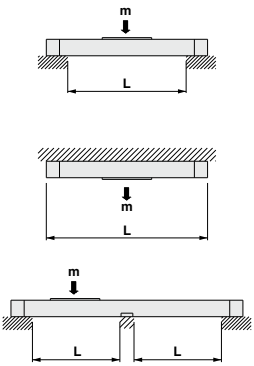


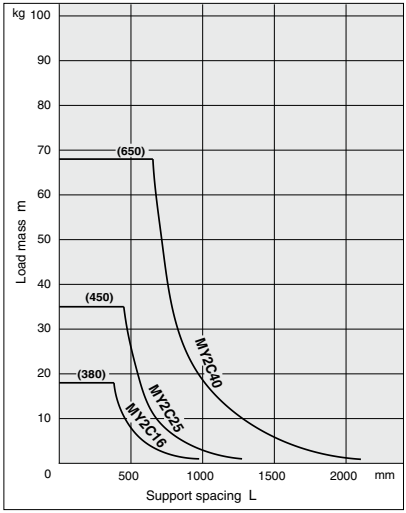
Model	Applicable cylinder	A	B	C	D	E	F	G	øH
MYC-S16A	**MY2C16**	60.6	64.6	70.6	77.2	15	26	4.9	3.4
MYC-S25A	**MY2C25**	95.9	97.5	107.9	115.5	25	38	6.4	4.5
MYC-S40A	**MY2C40**	121.5	121.5	134.5	145.5	45	64	11.7	6.6

* A set of side supports consists of a left support and a right support.

Guide for Using Side Support

For long stroke operation, the cylinder tube may deflect due to its own weight and/or load mass. In such cases, install a side support at the intermediate stroke position. The spacing (L) of the side support must be no more than the values shown in the graph at right.





⚠ Caution

① If the cylinder mounting surfaces are not measured accurately, using a side support may cause poor operation. Make sure to level the cylinder tube when mounting the cylinder. For long stroke operation involving vibration and impact, the use of side supports is recommended even if the support spacing is within the allowable limits shown in the graph.

② Support brackets are not for mounting. They should be used only to provide support.

Mechanically Jointed Rodless Cylinder Linear Guide Type

MY2H/HT Series

ø16, ø25, ø40

How to Order

Linear Guide Type **MY2 H 16 ☐ G – 300 ☐ – M9NW ☐ – ☐**

Guide type

H	Linear guide, Single axis
HT	Linear guide, Double axis

Bore size

16	16 mm
25	25 mm
40	40 mm

Port thread type

Symbol	Type	Bore size
Nil	M thread	ø16
	Rc	ø25, ø40
TN	NPT	
TF	G	

Piping

G	Centralized piping type (Standard)

Cylinder stroke (mm)

Bore size	Standard stroke	Intermediate stroke	Long stroke	Maximum manufacturable stroke
16	50, 100, 150 200, 250, 300	Intermediate strokes of 51 to 599 mm (1 mm increments) other than standard strokes	Strokes of 601 to 1000 mm (1 mm increments) exceeding the standard stroke	1000
25, 40	350, 400, 450 500, 550, 600		Strokes of 601 to 1500 mm (1 mm increments) exceeding the standard stroke	1500

Ordering example
∗ Intermediate stroke can be ordered the same as the standard stroke. MY2H16-60-M9BW
∗ Long stroke can be ordered the same as the standard stroke. MY2H25-800L-M9BW

Stroke adjustment unit symbol
Refer to "Stroke adjustment unit" on page 1105.

Auto switch

Nil	Without auto switch (Built-in magnet)

∗ Refer to the table below for the applicable auto switch model.

Number of auto switches

Nil	2 pcs.
S	1 pc.
n	"n" pcs.

Made to Order
Refer to page 1105 for details.

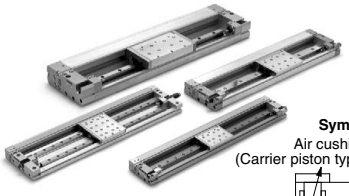
Applicable Auto Switches/Refer to pages 1289 to 1383 for further information on auto switches.

Type	Special function	Electrical entry	Indicator light	Wiring (Output)	Load voltage DC	Load voltage AC	Auto switch model Perpendicular	Auto switch model In-line	Lead wire length (m) 0.5 (Nil)	1 (M)	3 (L)	5 (Z)	Pre-wired connector	Applicable load	
Solid state auto switch	——	Grommet	Yes	3-wire (NPN)	5 V, 12 V	—	**M9NV**	**M9N**	●	●	●	○	○	IC circuit	Relay, PLC
				3-wire (PNP)			**M9PV**	**M9P**	●	●	●	○	○		
				2-wire	12 V		**M9BV**	**M9B**	●	●	●	○	○	—	
	Diagnostic indication (2-color indicator)			3-wire (NPN)	5 V, 12 V		**M9NWV**	**M9NW**	●	●	●	○	○	IC circuit	
				3-wire (PNP)			**M9PWV**	**M9PW**	●	●	●	○	○		
				2-wire	12 V		**M9BWV**	**M9BW**	●	●	●	○	○	—	
	Water resistant (2-color indicator)			3-wire (NPN)	5 V, 12 V		**M9NAV**∗1	**M9NA**∗1	○	○	●	○	○	IC circuit	
				3-wire (PNP)			**M9PAV**∗1	**M9PA**∗1	○	○	●	○	○		
				2-wire	12 V		**M9BAV**∗1	**M9BA**∗1	○	○	●	○	○	—	
Reed auto switch	——	Grommet	Yes	3-wire (NPN equivalent)	—	5 V	—	**A96V**	**A96**	●	—	●	—	—	IC circuit	—
			No	2-wire	24 V	12 V	100 V	**A93V**∗2	**A93**	●	●	●	●	—	—	Relay, PLC
							100 V or less	**A90V**	**A90**	●	—	●	—	—	IC circuit	

∗ Lead wire length symbols: 0.5 m ····· Nil (Example) M9NW
1 m ····· M (Example) M9NWM
3 m ····· L (Example) M9NWL
5 m ····· Z (Example) M9NWZ

∗ Solid state auto switches marked with "○" are produced upon receipt of order.

∗ There are other applicable auto switches than listed above. For details, refer to page 1114.
∗ For details about auto switches with pre-wired connector, refer to pages 1358 and 1359.
∗ Auto switches are shipped together (not assembled). (Refer to page 1114 for the details of auto switch mounting.)



Symbol
Air cushion
(Carrier piston type)

Made to Order

Made to Order: Individual Specifications
(For details, refer to page 1115.)

Symbol	Specifications
-X168	Helical insert thread

Symbol	Specifications
-XB20	Stroke adjusting unit with adjusting bolt
-XB22	Shock absorber soft type RJ series type
-XC56	With knock pin holes

Specifications

Bore size (mm)	16	25	40
Fluid	Air		
Action	Double acting		
Operating pressure range	0.15 to 0.8 MPa	0.1 to 0.8 MPa	
Proof pressure	1.2 MPa		
Ambient and fluid temperature	5 to 60°C		
Cushion	Air cushion, Shock absorber		
Lubrication	Not required (Non-lube)		
Stroke length tolerance	$^{+1.8}_{0}$		
Port size	M5 x 0.8	Rc 1/8	Rc 1/4

Piston Speed

Bore size (mm)		16	25	40
Without stroke adjustment unit		100 to 1000 mm/s Note 1)		
Stroke adjustment unit	**L unit and H unit**	100 to 1500 mm/s		

Note 1) When exceeding the air cushion stroke ranges on page 1092, the **piston speed** should be **100 to 200 mm/s.**
Note 2) Use at a piston speed within the absorption capacity range. Refer to page 1092.

Stroke Adjustment Unit Specifications

Bore size (mm)			16		25		40	
Unit symbol			**L**	**H**	**L**	**H**	**L**	**H**
Shock absorber model		**MY2H**	RB0806	RB1007	RB1007	RB1412	RB1412	RB2015
		MY2HT	RB1007	RB1412	RB1412	RB2015	RB2015	RB2725
Stroke adjustment range by intermediate fixing spacer (mm)	**Without spacer**		0 to –5.6		0 to –11.5		0 to –16	
	With short spacer		–5.6 to –11.2		–11.5 to –23		–16 to –32	
	With long spacer		–11.2 to –16.8		–23 to –34.5		–32 to –48	

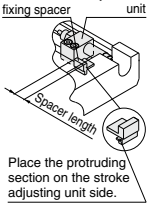
∗ Stroke adjustment range is applicable for one side when mounted on a cylinder.

Stroke Adjustment Unit Symbol

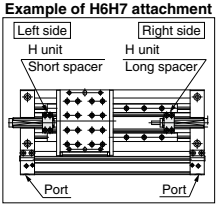
Left side stroke adjustment unit \ Right side stroke adjustment unit			Without unit	L: With low load shock absorber			H: With high load shock absorber		
					With short spacer	With long spacer		With short spacer	With long spacer
Without unit			**Nil**	**SL**	**SL6**	**SL7**	**SH**	**SH6**	**SH7**
L: With low load shock absorber			**LS**	**L**	**LL6**	**LL7**	**LH**	**LH6**	**LH7**
	With short spacer		**L6S**	**L6L**	**L6**	**L6L7**	**L6H**	**L6H6**	**L6H7**
	With long spacer		**L7S**	**L7L**	**L7L6**	**L7**	**L7H**	**L7H6**	**L7H7**
H: With high load shock absorber			**HS**	**HL**	**HL6**	**HL7**	**H**	**HH6**	**HH7**
	With short spacer		**H6S**	**H6L**	**H6L6**	**H6L7**	**H6H**	**H6**	**H6H7**
	With long spacer		**H7S**	**H7L**	**H7L6**	**H7L7**	**H7H**	**H7H6**	**H7**

∗ Spacers are used to fix the stroke adjustment unit at an intermediate stroke position.

Stroke adjustment unit mounting diagram



Example of H6H7 attachment



Shock Absorbers for L and H Units

Model	Type	Stroke adjustment unit	Bore size (mm) 16	25	40
MY2H	Standard (Shock absorber/RB series)	L	RB0806	RB1007	RB1412
		H	RB1007	RB1412	RB2015
	Shock absorber/soft type RJ series mounted (-XB22)	L	RJ0806H	RJ1007H	RJ1412H
		H	RJ1007H	RJ1412H	—
MY2HT	Standard (Shock absorber/RB series)	L	RB1007	RB1412	RB2015
		H	RB1412	RB2015	RB2725
	Shock absorber/soft type RJ series mounted (-XB22)	L	RJ1007H	RJ1412H	—
		H	RJ1412H	—	—

∗ The shock absorber service life is different from that of the MY2H/HT cylinder depending on operating conditions. Refer to the RB Series Specific Product Precautions for the replacement period.
∗ Mounted shock absorber soft type RJ series (-XB22) is made to order specifications. For details, refer to page 1468.

Shock Absorber Specifications

Model		RB 0806	RB 1007	RB 1412	RB 2015	RB 2725
Max. energy absorption (J)		2.9	5.9	19.6	58.8	147
Stroke absorption (mm)		6	7	12	15	25
Max. collision speed (mm/s)		1500	1500	1500	1500	1500
Max. operating frequency (cycle/min)		80	70	45	25	10
Spring force (N)	**Extended**	1.96	4.22	6.86	8.34	8.83
	Retracted	4.22	6.86	15.98	20.50	20.01
Operating temperature range (°C)		5 to 60				

∗ The shock absorber service life is different from that of the MY2H/HT cylinder depending on operating conditions. Refer to the RB Series Specific Product Precautions for the replacement period.

Theoretical Output

(N)

Bore size (mm)	Piston area (mm^2)	Operating pressure (MPa)						
		0.2	0.3	0.4	0.5	0.6	0.7	0.8
16	200	40	60	80	100	120	140	160
25	490	98	147	196	245	294	343	392
40	1256	251	377	502	628	754	879	1005

Note) Theoretical output (N) = Pressure (MPa) x Piston area (mm^2)

Replacement Parts

Drive Unit (Cylinder) Replacement Part No.

Bore size (mm) \ Model	MY2H	MY2HT
16	MY2BH16G- Stroke	
25	MY2BH25□G- Stroke	
40	MY2BH40□G- Stroke	

Enter a symbol for port thread type inside □.
Note) Order auto switches separately.

Weight

(kg)

Model	Bore size (mm)	Basic weight	Additional weight per each 50 mm of stroke	Weight of moving parts	Stroke adjustment unit weight (per unit)	
					L unit weight	H unit weight
MY2H	**16**	0.86	0.22	0.21	0.03	0.04
	25	2.35	0.42	0.64	0.06	0.09
	40	6.79	0.76	2.20	0.16	0.22
MY2HT	**16**	1.27	0.31	0.33	0.04	0.08
	25	3.70	0.61	1.20	0.10	0.18
	40	10.05	1.13	3.35	0.27	0.46

Calculation: (Example) **MY2H25G-300L**
- Basic weight ····· 2.35 kg
- Cylinder stroke ····· 300 stroke
- Additional weight ····· 0.42/50 stroke
  2.35 + 0.42 x 300/50 + 0.06 x 2 ≅ 4.99 kg
- Weight of L unit ····· 0.06 kg

Option

Stroke Adjustment Unit Part No.

MY 2H – A 25 L2 – 6N

Guide type

2H	MY2H16
2H	MY2H25
2H	MY2H40
2HT	MY2HT16
2HT	MY2HT25
2HT	MY2HT40

Stroke adjustment unit

Bore size

16	16 mm
25	25 mm
40	40 mm

Unit no.

Symbol	Stroke adjustment unit	Mounting position
L1	L unit	Left
L2		Right
H1	H unit	Left
H2		Right

Note) Refer to page 1105 for details about adjustment range.

Intermediate fixing spacer

Nil	Without spacer
6□	Short spacer
7□	Long spacer

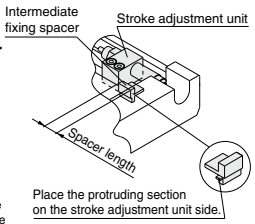
Spacer delivery type

Nil	Unit installed
N	Spacer only

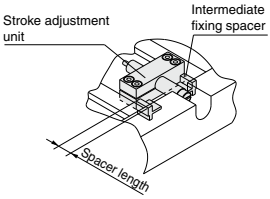
∗ Spacers are used to fix the stroke adjustment unit at an intermediate stroke position.
∗ Spacers are shipped for a set of two.

∗ When ordering the intermediate fixing spacer for the stroke adjustment unit, the intermediate fixing spacer is shipped together.

MY2H

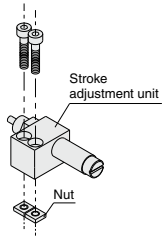


MY2HT

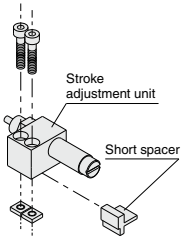


Component Parts

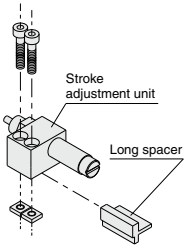
MY2H-A25L2 (Without spacer)



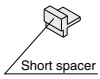
MY2H-A25L2-6 (With short spacer)



MY2H-A25L2-7 (With long spacer)



MY2H-A25L2-6N (Short spacer only)

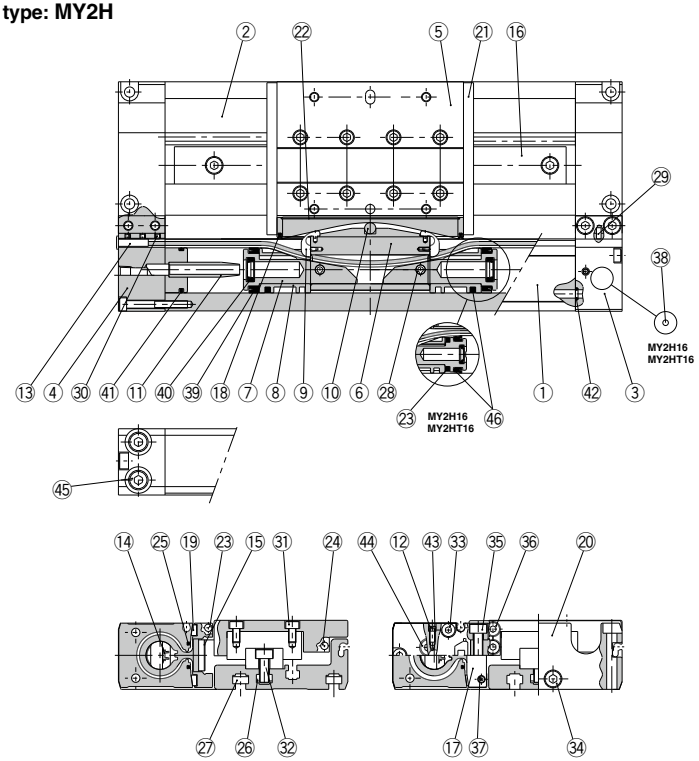


MY2H-A25L2-7N (Long spacer only)

∗ Nuts are equipped on the cylinder body.

Construction

Single axis type: MY2H

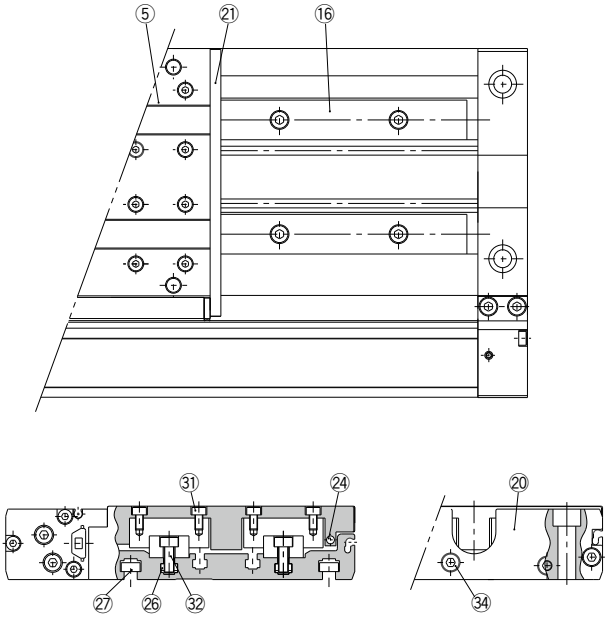


Component Parts

No.	Description	Material	Note
1	**Cylinder tube**	Aluminum alloy	Hard anodized
2	**Body**	Aluminum alloy	Anodized
3	**Head cover WR**	Aluminum alloy	Hard anodized
4	**Head cover WL**	Aluminum alloy	Hard anodized
5	**Slide table**	Aluminum alloy	Hard anodized
6	**Piston yoke**	Aluminum alloy	Hard anodized
7	**Piston**	Aluminum alloy	Chromated
8	**Wear ring**	Special resin	
9	**Belt separator**	Special resin	
10	**Parallel pin**	Stainless steel	
11	**Cushion ring**	Aluminum alloy	Anodized
12	**Cushion needle**	Rolled steel	Nickel plated
13	**Belt clamp**	Special resin	
16	**Guide**	—	
17	**End cover**	Aluminum alloy	Hard anodized
19	**Bearing**	Special resin	
20	**End plate**	Aluminum alloy	Hard anodized
21	**Stopper**	Carbon steel	Nickel plated after quenching
22	**Top cover**	Stainless steel	

No.	Description	Material	Note
23	**Magnet**	—	
24	**Magnet**	—	
25	**Seal magnet**	Rubber magnet	
26	**Square nut**	Carbon steel	Chromated
27	**Square nut**	Carbon steel	Chromated
28	**Spring pin**	Carbon tool steel	
29	**Parallel pin**	Stainless steel	
30	**Hexagon socket set screw**	Chrome molybdenum steel	Black zinc chromated
31	**Hexagon socket head cap screw**	Chrome molybdenum steel	Chromated
32	**Hexagon socket head cap screw**	Chrome molybdenum steel	Chromated
33	**Hexagon socket head cap screw**	Chrome molybdenum steel	Chromated
34	**Hexagon socket head cap screw**	Chrome molybdenum steel	Chromated
35	**Hexagon socket head cap screw**	Chrome molybdenum steel	Chromated
36	**Hexagon socket head cap screw**	Chrome molybdenum steel	Chromated
37	**Hexagon socket head cap screw**	Chrome molybdenum steel	Chromated
38	**Steel ball**	Spring steel	Nickel plated
44	**Hexagon socket head (taper) plug**	Carbon steel	Chromated
45	**Hexagon socket head (taper) plug**	Carbon steel	Chromated
46	**Lubretainer**	Special resin	

Double axis type: MY2HT



Replacement Parts: Seal Kit

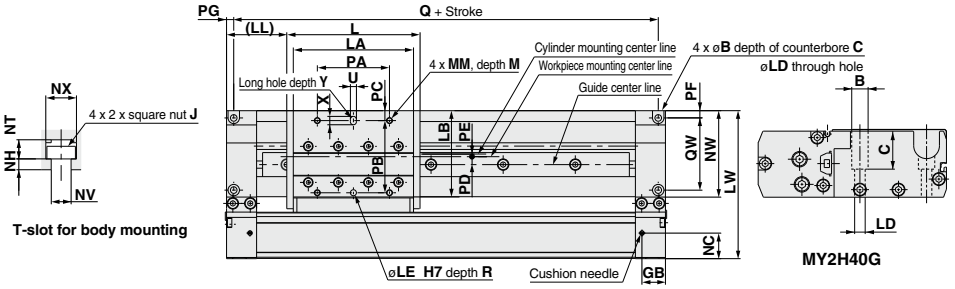
No.	Description	Qty.	MY2H16G/MY2HT16G	MY2H25G/MY2HT25G	MY2H40G/MY2HT40G
14	**Seal belt**	1	MY16-16C-Stroke	MY25-16C-Stroke	MY40-16C-Stroke
15	**Dust seal band**	1	MY2H16-16B-Stroke	MY2H25-16B-Stroke	MY2H40-16B-Stroke
43	**O-ring**	2	KA00309 (ø4 x ø1.8 x ø1.1)	KA00309 (ø4 x ø1.8 x ø1.1)	KA00320 (ø7.15 x ø3.75 x ø1.7)
18	**Scraper**	2	MY2B16-PS	MY2B25-PS	MY2B40-PS
39	**Piston seal**	2			
40	**Cushion seal**	2			
41	**Tube gasket**	2			
42	**O-ring**	4			

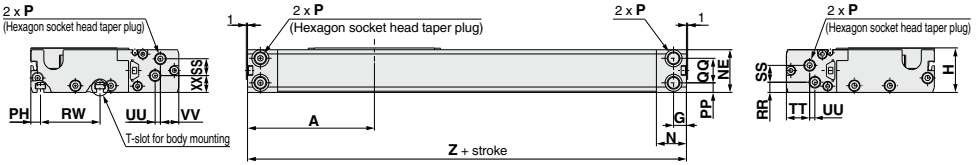
∗ Seal kit includes ⑱, ㊴, ㊵, ㊶ and ㊷. Order the seal kit based on each bore size.
∗ Seal kit includes a grease pack (10 g).
When ⑭ and ⑮ are shipped as single units, a grease pack (20 g) is included.
Order with the following part number when only the grease pack is needed.
Grease pack part number:GR-S-010 (10 g) **, GR-S-020** (20 g)

Single Axis Type: ø16, ø25, ø40

Refer to page 1118 regarding port variations.

MY2H Bore size **G –** Stroke





(mm)

Model	A	B	C	G	GB	H	L	J	LA	LB	LD	LE	(LL)	LW	M	MM	N	NC	NE	NH	NT	NV	NW	NX	P
MY2H16G	80	6.5	3.3	8.5	17	28	80	M3 x 0.5	70	50.4	3.4	4	40	83	7	M4 x 0.7	20	14	27	2	3.5	3.4	48.2	5.8	M5 x 0.8
MY2H25G	105	9.5	5.4	10.7	19.5	37	110.8	M5 x 0.8	100	71.7	5.5	5	49.6	123	9	M5 x 0.8	25	21.3	35.5	3	5.3	5.5	71.8	8.5	$1/8$
MY2H40G	165	14	32.5	15.5	31.5	58	180	M6 x 1	158	80.3	9	6	75	161	13	M6 x 1	40	32.4	56.5	4	6.5	6.6	82.1	10.5	$1/4$

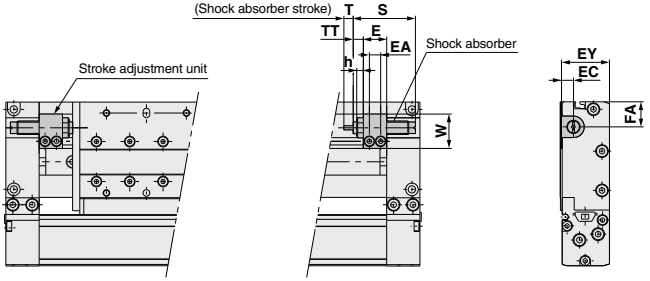
Model	PA	PB	PC	PD	PE	PF	PG	PH	PP	Q	QQ	QW	R	RR	RW	SS	TT	U	UU	VV	X	XX	Y	Z
MY2H16G	40	40	7.2	2.8	3.7	3.5	4	5.1	5.3	152	16.4	40	5	5.3	40	9.7	12.5	4	3	10.5	6	12	5	160
MY2H25G	60	60	8.2	6.6	2.7	5.5	6	7.5	8	198	20.4	60	5	8.5	50	14	19.3	5	4.4	15.3	7.5	14	5	210
MY2H40G	100	70	5.5	8.5	5	17	9	9.5	16	312	25.5	57	8	11	53.5	21.5	35.4	6	2	29	9	23	8	330

"P" indicates cylinder supply ports. ∗ The plug for "P" MY2H16G is a hexagon socket head plug.

Stroke adjustment unit

Low load shock absorber

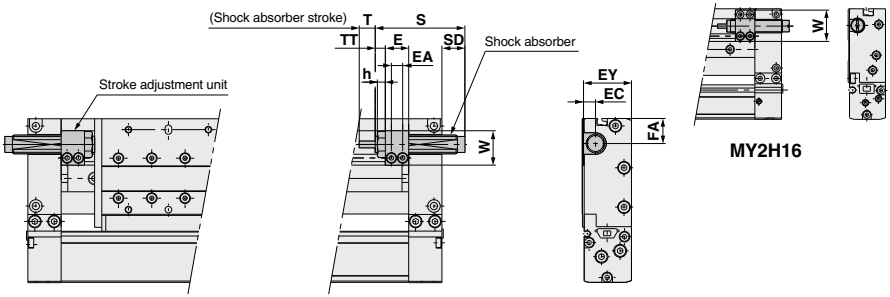
MY2H Bore size G – Stroke L



Applicable cylinder	E	EA	EC	EY	FA	h	S	T	TT	W	Shock absorber model
MY2H16	14.4	7	6	27	12.5	4	40.8	6	5.6 (Max. 11.2)	16.5	RB0806
MY2H25	17.5	8.5	9	36	19.3	5	46.7	7	7.1 (Max. 18.6)	25.8	RB1007
MY2H40	25	13	13	57	17	6	67.3	12	10 (Max. 26)	38	RB1412

High load shock absorber

MY2H Bore size G – Stroke H

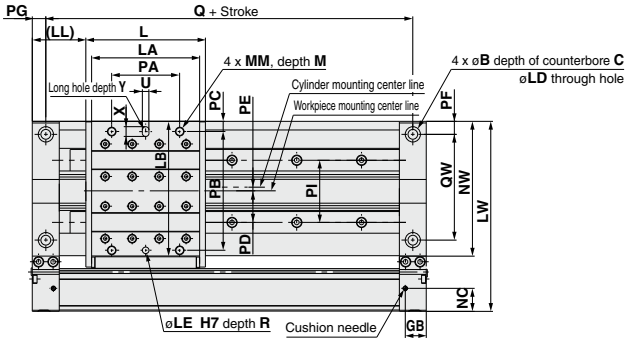


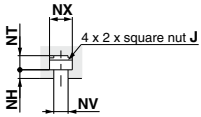
Applicable cylinder	E	EA	EC	EY	FA	h	S	SD	T	TT	W	Shock absorber model
MY2H16	14.4	7	6	27	12.5	—	46.7	6.7	7	5.6 (Max. 11.2)	23.5	RB1007
MY2H25	17.5	8.5	9	36	19.3	6	67.3	17.7	12	7.1 (Max. 18.6)	25.8	RB1412
MY2H40	25	13	13	57	17	6	73.2	—	15	10 (Max. 26)	38	RB2015

Double Axis Type: ø16, ø25, ø40

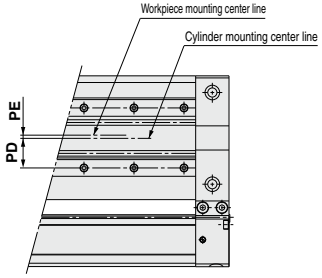
Refer to page 1118 regarding port variations.

MY2HT Bore size G – Stroke

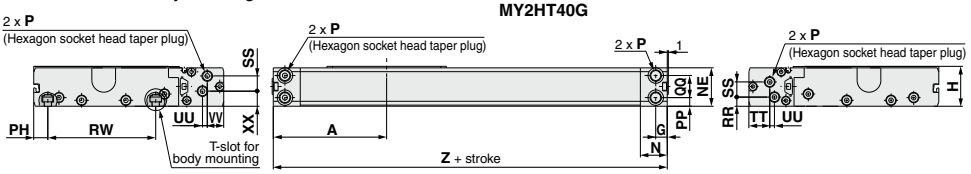




T-slot for body mounting



MY2HT40G



Model	A	B	C	G	GB	H	L	J	LA	LB	LD	LE	(LL)	LW	M	MM	N	NC	NE	NH	NT
MY2HT16G	80	9.5	5.4	8.5	17	28	80	M4 x 0.7	70	87.4	5.5	5	40	120	9	M5 x 0.8	20	14	27	3	4.7
MY2HT25G	105	14	8.6	10.7	19.5	37	110.8	M6 x 1	100	124.7	9	6	49.6	176	12	M8 x 1.25	25	21.3	35.5	4	6.5
MY2HT40G	165	17.5	10.8	15.5	31.5	58	180	M8 x 1.25	158	148.3	11	8	75	229	16	M10 x 1.5	40	32.4	56.5	5	9

Model	NV	NW	NX	P	PA	PB	PC	PD	PE	PF	PG	PH	PI	PP	Q	QQ	QW	R	RR	RW	SS	TT
MY2HT16G	4.5	85.2	7.3	M5 x 0.8	44	80	4	23	1	10	10	10.2	41	5.3	140	16.4	66	5	5.3	69	9.7	12.5
MY2HT25G	6.6	124.8	10.5	$^1/_8$	63	110	9.4	29.2	3.4	12	12.5	13	57.6	8	185	20.4	98	8	8.5	100	14	19.3
MY2HT40G	9	150.1	14	$^1/_4$	113	132	8.5	35.5	0.5	20	20	18.5	72	16	290	25.5	110	12	11	116	21.5	35.4

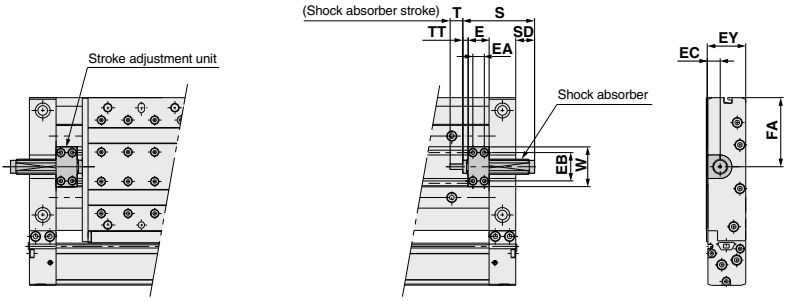
Model	U	UU	VV	X	XX	Y	Z
MY2HT16G	5	3	10.5	7	12	5	160
MY2HT25G	6	4.4	15.3	9	14	8	210
MY2HT40G	8	2	29	12	23	12	330

"P" indicates cylinder supply ports. * The plug for "P" MY2HT16G is a hexagon socket head plug.

Stroke adjustment unit

Low load shock absorber

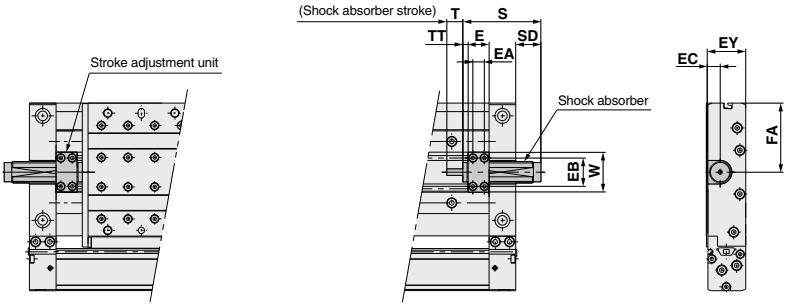
MY2HT Bore size G – Stroke L



Applicable cylinder	E	EA	EB	EC	EY	FA	S	SD	T	TT	W	Shock absorber model
MY2HT16	14.4	7	21	8	27	46.5	46.7	6.7	7	5.6 (Max. 11.2)	28.6	RB1007
MY2HT25	19.7	10.7	26.6	11.2	36	64.8	67.3	17.7	12	4.9 (Max. 16.4)	37.2	RB1412
MY2HT40	29.1	15.1	37	17.2	57	74.5	73.2	—	15	5.9 (Max. 21.9)	51.6	RB2015

High load shock absorber

MY2HT Bore size G – Stroke H

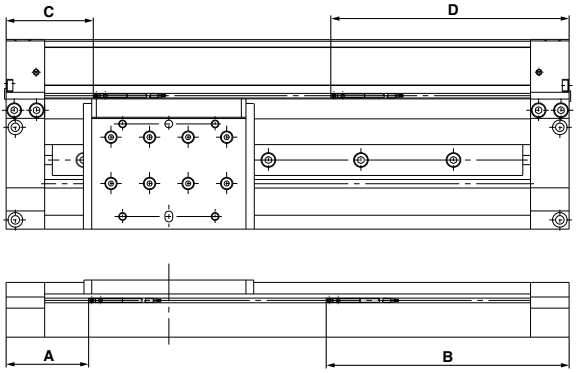


Applicable cylinder	E	EA	EB	EC	EY	FA	S	SD	T	TT	W	Shock absorber model
MY2HT16	14.4	7	21	8	27	46.5	67.3	27.3	12	5.6 (Max. 11.2)	28.6	RB1412
MY2HT25	19.7	10.7	26.6	11.2	36	64.8	73.2	23.6	15	4.9 (Max. 16.4)	37.2	RB2015
MY2HT40	29.1	15.1	37	17.2	57	74.5	99	24	25	5.9 (Max. 21.9)	51.6	RB2725

Auto Switch Mounting

Proper Auto Switch Mounting Position (Detection at stroke end)

Note) The operating range is a standard including hysteresis, and is not guaranteed. There may be large variations depending on the surrounding environment (variations on the order of ±30%).



D-A9□, D-A9□V

Series model	A	B	Operating range
MY2C16	44	116	11
MY2H16	46	114	
MY2HT16	70	90	
MY2C/H/HT25	54	156	
MY2C/H/HT40	85	245	

Series model	C	D	Operating range
MY2C/H/HT16	27.6	132.4	6.5
MY2C/H/HT25	69	141	11
MY2C/H/HT40	90.2	239.8	

D-M9□, D-M9□V, D-M9□W, D-M9□WV, D-M9□A, D-M9□AV

Series model	A	B	Operating range
MY2C16	48	112	8.5
MY2H16	50	110	
MY2HT16	74	86	
MY2C/H/HT25	58	152	
MY2C/H/HT40	89	241	

Series model	C	D	Operating range
MY2C/H/HT16	31.6	128.4	4
MY2C/H/HT25	73	137	8.5
MY2C/H/HT40	94.2	235.8	

* Adjust the auto switch after confirming the operating conditions in the actual setting.

Besides the models listed in How to Order, the following auto switches are applicable.

* For solid state auto switches, auto switches with a pre-wired connector are also available. Refer to pages 1358 and 1359 for details.
* Normally closed (NC = b contact) solid state auto switches (D-M9□E(V)) are also available. Refer to page 1308 for details.

MY2 Series
Made to Order: Individual Specifications

Made to Order

1 Helical Insert Thread Specifications

Symbol
-X168

Helical insert thread is used for the slide table mounting thread, the thread size is the same as the standard model.

MY2 □ **Bore size** − **Stroke** − **Auto switch** **Suffix** −**X168**

Series: Bore size

		16	25	40
C	Cam follower guide type	●	●	●
H	Linear guide type (Single axis)	●	●	●
HT	Linear guide type (Double axis)	●	●	●

Example) **MY2H40G-300L-A93-X168**

MY2 Series
Specific Product Precautions 1

Be sure to read this before handling the products. Refer to page 8 for safety instructions and pages 9 to 18 for actuator and auto switch precautions.

Selection

⚠Caution

1. When using a cylinder with long strokes, implement an intermediate support.

When using a cylinder with long strokes, implement an intermediate support to prevent the tube from sagging and being deflected by vibration or an external load.
Refer to the Guide for Side Support Application (MY2C series) on page 1102.

2. For intermediate stops, use a dual-side pressure control circuit.

Since the mechanically jointed rodless cylinders have a unique seal structure, slight external leakage may occur. Controlling intermediate stops with a 3 position valve cannot hold the stopping position of the slide table (slider). The speed at the restarting state also may not be controllable. Use the dual-side pressure control circuit with a PAB-connected 3 position valve for intermediate stops.

3. Constant speed

Since the mechanically jointed rodless cylinders have a unique seal structure, a slight speed change may occur. For applications that require constant speed, select an applicable equipment for the level of demand.

4. Load factor of 0.5 or less

When the load factor is high against the cylinder output, it may adversely affect the cylinder (condensation, etc.) and cause malfunctions. Select a cylinder to make the load factor less than 0.5. (Mainly when using an external guide)

5. Cautions on less frequent operation

When the cylinder is used extremely infrequently, operation may be interrupted in order for anchoring and a change lubrication to be performed or service life may be reduced.

6. Consider uncalculated loads such as piping, cableveyor, etc., when selecting a load moment

Calculation does not include the external acting force of piping, cableveyor, etc. Select load factors taking into account the external acting force of piping, cableveyor, etc.

7. Accuracy

The mechanical jointed rodless cylinder does not guarantee traveling parallelism.

Mounting

⚠Caution

1. Do not apply a strong impact or moment on the slide table (slider).

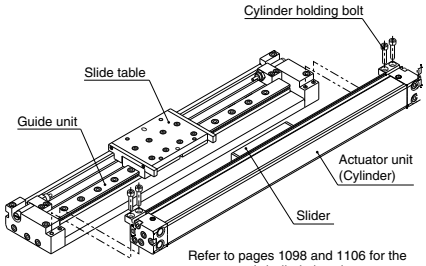
Since the slide table (slider) is supported by precision bearings, do not subject it to strong impact or excessive moment when mounting workpieces.

2. When connecting to a load which has an external guide mechanism, use a discrepancy absorption mechanism.

A mechanically jointed rodless cylinder can be used with a direct load within the allowable range for each guide type, however, align carefully when connecting to a load with an external guide mechanism.

3. Attaching and detaching the actuator unit (cylinder)

When detaching the actuator unit, remove the four cylinder holding bolts and take the actuator unit off the guide unit. When attaching the actuator unit, insert the slider into the slide table on the guide unit, and tighten the four holding bolts equally. Since loosened holding bolts may cause damage or malfunction, be sure to secure them tightly.



Refer to pages 1098 and 1106 for the actuator unit (cylinder) replacement part numbers.

MY2 Series
Specific Product Precautions 2

Be sure to read this before handling the products. Refer to page 8 for safety instructions and pages 9 to 18 for actuator and auto switch precautions.

Mounting

⚠Caution

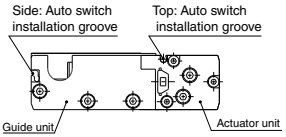
4. Auto Switch Mounting

The MY2 series can be equipped with auto switches on the top of the actuator unit (cylinder) and on the side of the guide unit, but use caution in the following cases.

<Mounting an auto switch on the top of the actuator unit (cylinder)>

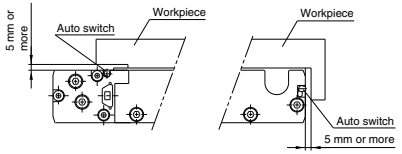
For auto switches with perpendicular electrical entry, the lead wire may interfere with the workpiece depending on the workpiece mounting type and shape.

Be sure to allow a clearance in order to keep the lead wire from interfering with the workpiece.



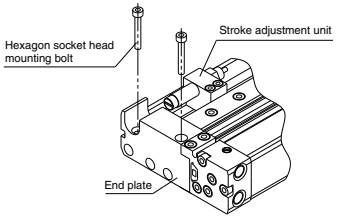
5. Workpiece Mounting

When mounting a magnetic workpiece, the auto switch may stop working due to a loss of magnetic force in the cylinder depending on the mounting position. Allow a clearance of 5 mm or more between the auto switch and workpiece.



6. Body Mounting

When mounting MY2H40G with stroke adjustment unit from the top, move the stroke adjustment unit and secure the body with the end plate mounting holes. After mounting, return the stroke adjustment unit to the stroke end and secure it again.



7. Do not generate negative pressure in the cylinder tube.

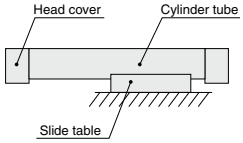
Take precautions under operating conditions in which negative pressure is generated inside the cylinder by external forces or inertial forces. Air leakage may occur due to separation of the seal belt. Do not generate negative pressure in the cylinder by forcibly moving it with an external force during the trial operation or dropping it with self-weight under the non-pressure state, etc. When the negative pressure is generated, slowly move the cylinder by hand and move the stroke back and forth. (When using with a stroke adjustment unit, please either remove the unit or adjust the stroke to the full stroke.)

8. Do not mount cylinders as they are twisted.

When mounting, be sure for a cylinder tube not to be twisted. The flatness of the mounting surface is not appropriate, the cylinder tube is twisted, which may cause air leakage due to the detachment of a seal belt, damage a dust seal band, and cause malfunctions.

9. Do not mount a slide table on the fixed equipment surface.

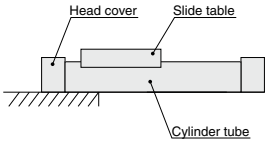
It may cause damage or malfunctions since an excessive load is applied to the bearing.



Mounting with a slide table (slider)

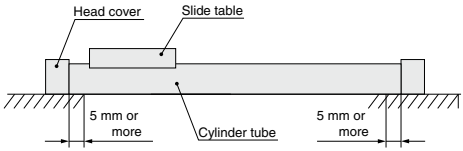
10. Do not mount in a cantilevered way.

Since the cylinder body deflects, it may cause malfunctions.



Mounting in a cantilevered way

11. Fixed parts of the cylinder on both ends must have at least 5 mm of contact between where the bottom of the cylinder tube and the equipment surface.



12. Consider uncalculated loads such as piping, cableveyor, etc., when selecting a load moment

Calculation does not include the external acting force of piping, cableveyor, etc. Select load factors taking into account the external acting force of piping, cableveyor, etc.

13. Do not unnecessarily alter the guide adjustment setting.

The adjustment of the guide is preset and does not require readjustment under normal operating conditions. Therefore, do not unnecessarily alter the guide adjustment setting.

MY2 Series
Specific Product Precautions 3

Be sure to read this before handling the products. Refer to page 8 for safety instructions and pages 9 to 18 for actuator and auto switch precautions.

Operating Environment

⚠ Warning

1. Do not use in environments where the cylinder will come in contact with coolants, cutting oil, water drops, adhesive foreign particles, dust, etc., and do not operate the cylinder with compressed air that contains drainage and foreign matter.

Foreign matter or liquids on the cylinder interior or exterior can wash away the lubricating grease, which can lead to deterioration and damage of the dust seal band and seal materials, causing a danger of malfunction.

When operating in locations with exposure to water, oil drops, or dust, provide protection such as a cover to prevent direct contact with the cylinder, or mount the dust seal band surface downwards, and operate it with clean compressed air.

2. Carry out cleaning and grease application suitable for the operating environment.

Carry out cleaning regularly when using in an operating environment in which the product is likely to get dirty.

After cleaning, be sure to apply grease to the top side of the cylinder tube and the rotating part of the dust seal band. Apply grease to these parts regularly even if not after cleaning.

Service Life and Replacement Period of Shock Absorber

⚠ Caution

1. Allowable operating cycle under the specifications set in this catalog is shown below.

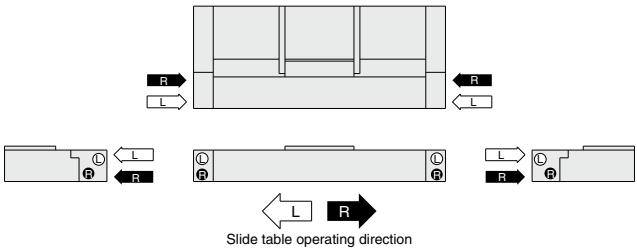
1.2 million times RB08□□
2 million times RB10□□ to RB2725

Note) Specified service life (suitable replacement period) is the value at room temperature (20 to 25 °C). The period may vary depending on the temperature and other conditions. In some cases the absorber may need to be replaced before the allowable operating cycle above.

Centralized Piping Port Variations

⚠ Caution

Head cover piping connection can be freely selected to best suit different piping conditions.

Applicable cylinder	Port variation
MY2C16/25/40 **MY2H16/25/40** **MY2HT16/25/40**	 Slide table operating direction